
Neural Monkey Documentation

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Neural Monkey is an open-source toolkit for sequence learning using Tensorflow.
If you want to dig in the code, you can browse the [repository](#).

1.1 Installation

Before you start, make sure that you already have installed Python 3.5, pip and git.

Create and activate a virtual environment to install the package into:

```
$ python3 -m venv nm
$ source nm/bin/activate
# after this, your prompt should change
```

Then clone Neural Monkey from GitHub and switch to its root directory:

```
(nm)$ git clone https://github.com/ufal/neuralmonkey
(nm)$ cd neuralmonkey
```

Run pip to install all requirements. For the CPU version install dependencies by this command:

```
(nm)$ pip install --upgrade -r requirements.txt
```

For the GPU version install dependencies try this command:

```
(nm)$ pip install --upgrade -r requirements-gpu.txt
```

If you are using the GPU version, make sure that the `LD_LIBRARY_PATH` environment variable points to `lib` and `lib64` directories of your CUDA and CuDNN installations. Similarly, your `PATH` variable should point to the `bin` subdirectory of the CUDA installation directory.

You made it! Neural Monkey is now installed!

1.1.1 Note for Ubuntu 14.04 Users

If you get Segmentation fault errors at the very end of the training process, you can either ignore it, or follow the steps outlined in [this document](#).

1.2 Package Overview

This overview should provide you with the basic insight on how Neural Monkey conceptualizes the problem of sequence-to-sequence learning and how the data flow during training and running models looks like.

1.2.1 Loading and Processing Datasets

We call a *dataset* a collection of named data *series*. By a series we mean a list of data items of the same type representing one type of input or desired output of a model. In the simple case of machine translation, there are two series: a list of source-language sentences and a list of target-language sentences.

The following scheme captures how a dataset is created from input data.

The dataset is created in the following steps:

1. An input file is read using a *reader*. Reader can e.g., load a file containing paths to JPEG images and load them as `numpy` arrays, or read a tokenized text as a list of lists (sentences) of string tokens.
2. Series created by the readers can be preprocessed by some *series-level preprocessors*. An example of such preprocessing is byte-pair encoding which loads a list of merges and segments the text accordingly.
3. The final step before creating a dataset is applying *dataset-level* preprocessors which can take more series and output a new series.

Currently there are two implementations of a dataset. An in-memory dataset which stores all data in the memory and a lazy dataset which gradually reads the input files step by step and only stores the batches necessary for the computation in the memory.

1.2.2 Training and Running a Model

This section describes the training and running workflow. The main concepts and their interconnection can be seen in the following scheme.

The dataset series can be used to create a *vocabulary*. A vocabulary represents an indexed set of tokens and provides functionality for converting lists of tokenized sentences into matrices of token indices and vice versa. Vocabularies are used by encoders and decoders for feeding the provided series into the neural network.

The model itself is defined by *encoders* and *decoders*. Most of the TensorFlow code is in the encoders and decoders. Encoders are parts of the model which take some input and compute a representation of it. Decoders are model parts that produce some outputs. Our definition of encoders and decoders is more general than in the classical sequence-to-sequence learning. An encoder can be for example a convolutional network processing an image. The RNN decoder is for us only a special type of decoder, it can be also a sequence labeler or a simple multilayer-perceptron classifier.

Decoders are executed using so-called *runners*. Different runners represent different ways of running the model. We might want to get a single best estimation, get an n-best list or a sample from the model. We might want to use an RNN decoder to get the decoded sequences or we might be interested in the word alignment obtained by its attention model. This is all done by employing different runners over the decoders. The outputs of the runners can be subject of further *post-processing*.

Additionally to runners, each training experiment has to have its *trainer*. A *trainer* is a special case of a runner that actually modifies the parameters of the model. It collects the objective functions and uses them in an optimizer.

Neural Monkey manages TensorFlow sessions using an object called *TensorFlow manager*. Its basic capability is to execute runners on provided datasets.

1.3 Post-Editing Task Tutorial

This tutorial will guide you through designing your first experiment in Neural Monkey.

Before we get started with the tutorial, please check that you have the Neural Monkey package properly *installed and working*.

1.3.1 Part I. - The Task

This section gives an overall description of the task we will try to solve in this tutorial. To make things more interesting than plain machine translation, let's try automatic post-editing task (APE, rhyming well with Neural Monkey).

In short, automatic post-editing is a task, in which we have a source language sentence (let's call it f , as grown-ups do), a machine-translated sentence of f (I actually don't know what grown-ups call this, so let's call this e'), and we are expected to generate another sentence in the same language as e' but cleaned of all the errors that the machine translation system have made (let's call this cleaned sentence e). Consider this small example:

Source sentence f : Bärbel hat eine Katze.

Machine-translated sentence e' : Bärbel has a dog.

Corrected translation e : Bärbel has a cat.

In the example, the machine translation system wrongly translated the German word “Katze” as the English word “dog”. It is up to the post-editing system to fix this error.

In theory (and in practice), we regard the machine translation task as searching for a target sentence e^* that has the highest probability of being the translation given the source sentence f . You can put it to a formula:

$$e^* = \operatorname{argmax}_e p(e|f)$$

In the post-editing task, the formula is slightly different:

$$e^* = \operatorname{argmax}_e p(e|f, e')$$

If you think about this a little, there are two ways one can look at this task. One is that we are translating the machine-translated sentence from a kind of *synthetic* language into a proper one, with additional knowledge what the source sentence was. The second view regards this as an ordinary machine translation task, with a little help from another MT system.

In our tutorial, we will assume the MT system used to produce the sentence e' was good enough. We thus generally trust it and expect only to make small edits to the translated sentence in order to make it fully correct. This means that we don't need to train a whole new MT system that would translate the source sentences from scratch. Instead, we will build a system that will tell us how to edit the machine translated sentence e' .

1.3.2 Part II. - The Edit Operations

How can an automatic system tell us how to edit a sentence? Here's one way to do it: We will design a set of edit operations and train the system to generate a sequence of these operations. If we consider a sequence of edit operations a function R (as in *rewrite*), which transforms one sequence to another, we can adapt the formulas above to suit our needs more:

$$\begin{aligned} R^* &= \operatorname{argmax}_R p(R(e')|f, e') \\ e^* &= R^*(e') \end{aligned}$$

So we are searching for the best edit function R^* that, once applied to e' , will give us the corrected output e^* . Another question is what the class of all possible edit functions should look like, for now we simply limit them to functions that can be defined as sequences of edit operations.

The edit function R processes the input sequence token-by-token in left-to-right direction. It has a pointer to the input sequence, which starts by pointing to the first word of the sequence.

We design three types of edit operations as follows:

1. KEEP - this operation copies the current word to the output and moves the pointer to the next token of the input,
2. DELETE - this operation does not emit anything to the output and moves the pointer to the next token of the input,
3. INSERT - this operation puts a word on the output, leaving the pointer to the input intact.

The edit function applies all its operations to the input sentence. We handle malformed edit sequences simply: if the pointer reaches the end of the input sequence, operations KEEP and DELETE do nothing. If the sequence of edits ends before the end of the input sentence is reached, we apply as many additional KEEP operations as needed to reach the end of the input sequence.

Let's see another example:

```
Bärbel has a dog .
KEEP KEEP KEEP DELETE cat KEEP
```

The word “cat” on the second line is an INSERT operation parameterized by the word “cat”. If we apply all the edit operations to the input (i.e. keep the words “Bärbel”, “has”, “a”, and “.”, delete the word “dog” and put the word “cat” in its place), we get the corrected target sentence.

1.3.3 Part III. - The Data

We are going to use the data for WMT 16 shared APE task. You can get them at the [WMT 16 website](#) or directly at the [Lindat repository](#). There are three files in the repository:

1. TrainDev.zip - contains training and development data set
2. Test.zip - contains source and translated test data
3. test_pe.zip - contains the post-edited test data

Now - before we start, let's create our experiment directory, in which we will place all our work. We shall call it for example `exp-nm-ape` (feel free to choose another weird string).

Extract all the files into the `exp-nm-ape/data` directory. Rename the files and directories so you get this directory structure:

```
exp-nm-ape
|
\== data
|
|== train
| |
| |== train.src
| |== train.mt
| \== train.pe
|
|== dev
| |
| |== dev.src
| |== dev.mt
```

```

| \== dev.pe
|
\== test
|
|== test.src
|== test.mt
\== test.pe

```

The data is already tokenized so we don't need to run any preprocessing tools. The format of the data is plain text with one sentence per line. There are 12k training triplets of sentences, 1k development triplets and 2k of evaluation triplets.

Preprocessing of the Data

The next phase is to prepare the post editing sequences that we should learn during training. We apply the Levenshtein algorithm to find the shortest edit path from the translated sentence to the post-edited sentence. As a little coding exercise, you can implement your own script that does the job, or you may use our preprocessing script from the Neural Monkey package. For this, in the `neuralmonkey` root directory, run:

```

scripts/postedit_prepare_data.py \
  --translated-sentences=exp-nm-ape/data/train/train.mt \
  --target-sentences=exp-nm-ape/data/train/train.pe \
  > exp-nm-ape/data/train/train.edits

```

And the same for the development data.

NOTE: You may have to change the path to the `exp-nm-ape` directory if it is not located inside the repository root directory.

NOTE 2: There is a hidden option of the preparation script (`--target-german=True`) which turns on some steps tailored for better processing of German text. In this tutorial, we are not going to use it.

If you look at the preprocessed files, you will see that the KEEP and DELETE operations are represented with special tokens while the INSERT operations are represented simply with the word they insert.

Congratulations! Now, you should have `train.edits`, `dev.edits` and `test.edits` files all in their respective data directories. We can now move to work with Neural Monkey configurations!

1.3.4 Part IV. - The Model Configuration

In Neural Monkey, all information about a model and its training is stored in configuration files. The syntax of these files is a plain INI syntax (more specifically, the one which gets processed by Python's `ConfigParser`). The configuration file is structured into a set of sections, each describing a part of the training. In this section, we will go through all of them and write our configuration file needed for the training of the post-editing task.

First of all, create a file called `post-edit.ini` and put it inside the `exp-nm-ape` directory. Put all the snippets that we will describe in the following paragraphs into the file.

1 - Datasets

For training, we prepare two datasets. The first dataset will serve for the training, the second one for validation. In Neural Monkey, each dataset contains a number of so called *data series*. In our case, we will call the data series *source*, *translated*, and *edits*. Each of those series will contain the respective set of sentences.

It is assumed that all series within a given dataset have the same number of elements (i.e. sentences in our case).

The configuration of the datasets looks like this:

```
[train_dataset]
class=dataset.load_dataset_from_files
s_source="exp-nm-ape/data/train/train.src"
s_translated="exp-nm-ape/data/train/train.mt"
s_edits="exp-nm-ape/data/train/train.edits"

[val_dataset]
class=dataset.load_dataset_from_files
s_source="exp-nm-ape/data/dev/dev.src"
s_translated="exp-nm-ape/data/dev/dev.mt"
s_edits="exp-nm-ape/data/dev/dev.edits"
```

Note that series names (*source*, *translated*, and *edits*) are arbitrary and defined by their first mention. The `s_` prefix stands for “series” and is used only here in the dataset sections, not later when the series are referred to.

These two INI sections represent two calls to function `neuralmonkey.config.dataset_from_files`, with the series file paths as keyword arguments. The function serves as a constructor and builds an object for every call. So at the end, we will have two objects representing the two datasets.

2 - Vocabularies

Each encoder and decoder which deals with language data operates with some kind of vocabulary. In our case, the vocabulary is just a list of all unique words in the training data. Note that apart the special `<keep>` and `<delete>` tokens, the vocabularies for the *translated* and *edits* series are from the same language. We can save some memory and perhaps improve quality of the target language embeddings by share vocabularies for these datasets. Therefore, we need to create only two vocabulary objects:

```
[source_vocabulary]
class=vocabulary.from_dataset
datasets=[<train_dataset>]
series_ids=["source"]
max_size=50000

[target_vocabulary]
class=vocabulary.from_dataset
datasets=[<train_dataset>]
series_ids=["edits", "translated"]
max_size=50000
```

The first vocabulary object (called `source_vocabulary`) represents the (English) vocabulary used for this task. The 50,000 is the maximum size of the vocabulary. If the actual vocabulary of the data was bigger, the rare words would be replaced by the `<unk>` token (hardcoded in Neural Monkey, not part of the 50,000 items), which stands for unknown words. In our case, however, the vocabularies of the datasets are much smaller so we won’t lose any words.

Both vocabularies are created out of the training dataset, as specified by the line `datasets=[<train_dataset>]` (more datasets could be given in the list). This means that if there are any unseen words in the development or test data, our model will treat them as unknown words.

We know that the languages in the *translated* series and *edits* are the same (except for the `KEEP` and `DELETE` tokens in the *edits*), so we create a unified vocabulary for them. This is achieved by specifying `series_ids=[edits, translated]`. The one-hot encodings (or more precisely, indices to the vocabulary) will be identical for words in *translated* and *edits*.

3 - Encoders

Our network will have two inputs. Therefore, we must design two separate encoders. The first encoder will process source sentences, and the second will process translated sentences, i.e. the candidate translations that we are expected to post-edit. This is the configuration of the encoder for the source sentences:

```
[src_encoder]
class=encoders.recurrent.SentenceEncoder
rnn_size=300
max_input_len=50
embedding_size=300
dropout_keep_prob=0.8
attention_type=decoding_function.Attention
data_id="source"
name="src_encoder"
vocabulary=<source_vocabulary>
```

This configuration initializes a new instance of sentence encoder with the hidden state size set to 300 and the maximum input length set to 50. (Longer sentences are trimmed.) The sentence encoder looks up the words in a word embedding matrix. The size of the embedding vector used for each word from the source vocabulary is set to 300. The source data series is fed to this encoder. 20% of the weights is dropped out during training from the word embeddings and from the attention vectors computed over the hidden states of this encoder. Note the `name` attribute must be set in each encoder and decoder in order to prevent collisions of the names of Tensorflow graph nodes.

The configuration of the second encoder follows:

```
[trans_encoder]
class=encoders.recurrent.SentenceEncoder
rnn_size=300
max_input_len=50
embedding_size=300
dropout_keep_prob=0.8
attention_type=decoding_function.Attention
data_id="translated"
name="trans_encoder"
vocabulary=<target_vocabulary>
```

This config creates a second encoder for the `translated` data series. The setting is the same as for the first encoder, except for the different vocabulary and name.

4 - Decoder

Now, we configure perhaps the most important object of the training - the decoder. Without further ado, here it goes:

```
[decoder]
class=decoders.decoder.Decoder
name="decoder"
encoders=[<trans_encoder>, <src_encoder>]
rnn_size=300
max_output_len=50
embeddings_encoder=<trans_encoder>
dropout_keep_prob=0.8
use_attention=True
data_id="edits"
vocabulary=<target_vocabulary>
```

As in the case of encoders, the decoder needs its RNN and embedding size settings, maximum output length, dropout parameter, and vocabulary settings.

The outputs of the individual encoders are by default simply concatenated and projected to the decoder hidden state (of `rnn_size`). Internally, the code is ready to support arbitrary mappings by adding one more parameter here: `encoder_projection`.

Note that you may set `rnn_size` to `None`. Neural Monkey will then directly use the concatenation of encoder states without any mapping. This is particularly useful when you have just one encoder as in MT.

The line `embeddings_encoder=<trans_encoder>` means that the embeddings (including embedding size) are shared with `trans_encoder`.

The loss of the decoder is computed against the `edits` data series of whatever dataset the decoder will be applied to.

5 - Runner and Trainer

As their names suggest, runners and trainers are used for running and training models. The `trainer` object provides the optimization operation to the graph. In the case of the cross entropy trainer (used in our tutorial), the default optimizer is Adam and it is run against the decoder's loss, with added L2 regularization (controlled by the `l2_weight` parameter of the trainer). The runner is used to process a dataset by the model and return the decoded sentences, and (if possible) decoder losses.

We define these two objects like this:

```
[trainer]
class=trainers.cross_entropy_trainer.CrossEntropyTrainer
decoders=[<decoder>]
l2_weight=1.0e-8

[runner]
class=runners.runner.GreedyRunner
decoder=<decoder>
output_series="greedy_edits"
```

Note that a runner can only have one decoder, but during training you can train several decoders, all contributing to the loss function.

The purpose of the trainer is to optimize the model, so we are not interested in the actual outputs it produces, only the loss compared to the reference outputs (and the loss is calculated by the given decoder).

The purpose of the runner is to get the actual outputs and for further use, they are collected to a new series called `greedy_edits` (see the line `output_series=`) of whatever dataset the runner will be applied to.

6 - Evaluation Metrics

During validation, the whole validation dataset gets processed by the models and the decoded sentences are evaluated against a reference to provide the user with the state of the training. For this, we need to specify evaluator objects which will be used to score the outputted sentences. In our case, we will use BLEU and TER:

```
[bleu]
class=evaluators.bleu.BLEUEvaluator
name="BLEU-4"
```

7 - TensorFlow Manager

In order to handle global variables such as how many CPU cores TensorFlow should use, you need to specify a “TensorFlow manager”:

```
[tf_manager]
class=tf_manager.TensorFlowManager
num_threads=4
num_sessions=1
minimize_metric=True
save_n_best=3
```

8 - Main Configuration Section

Almost there! The last part of the configuration puts all the pieces together. It is called `main` and specifies the rest of the training parameters:

```
[main]
name="post editing"
output="exp-nm-ape/training"
runners=[<runner>]
tf_manager=<tf_manager>
trainer=<trainer>
train_dataset=<train_dataset>
val_dataset=<val_dataset>
evaluation=[("greedy_edits", "edits", <bleu>), ("greedy_edits", "edits", evaluators.
↳ter.TER)]
batch_size=128
runners_batch_size=256
epochs=100
validation_period=1000
logging_period=20
```

The `output` parameter specifies the directory, in which all the files generated by the training (used for replicability of the experiment, logging, and saving best models variables) are stored. It is also worth noting, that if the output directory exists, the training is not run, unless the line `overwrite_output_dir=True` is also included here.

The `runners`, `tf_manager`, `trainer`, `train_dataset` and `val_dataset` options are self-explanatory.

The parameter `evaluation` takes list of tuples, where each tuple contains: - the name of output series (as produced by some runner), `greedy_edits` here, - the name of the reference series of the dataset, `edits` here, - the reference to the evaluation algorithm, `<bleu>` and `evaluators.ter.TER` in the two tuples here.

The `batch_size` parameter controls how many sentences will be in one training mini-batch. When the model does not fit into GPU memory, it might be a good idea to start reducing this number before anything else. The larger the batch size, however, the sooner the training should converge to the optimum.

Runners are less memory-demanding, so `runners_batch_size` can be set higher than `batch_size`.

The `epochs` parameter specifies the number of passes through the training data that the training loop should do. There is no early stopping mechanism in Neural Monkey yet, the training can be resumed after the end, however. The training can be safely `ctrl+C`'ed in any time: Neural Monkey preserves the last `save_n_best` best model variables saved on the disk.

The validation and logging periods specify how often to measure the model's performance on the training batch (`logging_period`) or on validation data (`validation_period`). Note that both logging and validation involve running the runners over the current batch or the validation data, resp. If this happens too often, the time needed to train the model can significantly grow.

At each validation (and logging), the output is scored using the specified evaluation metrics. The last of the evaluation metrics (TER in our case) is used to keep track of the model performance over time. Whenever the score on validation data is better than any of the `save_n_best` (3 in our case) previously saved models, the model is saved, discarding unnecessary lower scoring models.

1.3.5 Part V. - Running an Experiment

Now that we have prepared the data and the experiment INI file, we can run the training. If your Neural Monkey installation is OK, you can just run this command from the root directory of the Neural Monkey repository:

```
bin/neuralmonkey-train exp-nm-ape/post-edit.ini
```

You should see the training program reporting the parsing of the configuration file, initializing the model, and eventually the training process. If everything goes well, the training should run for 100 epochs. You should see a new line with the status of the model's performance on the current batch every few seconds, and there should be a validation report printed every few minutes.

As given in the `main.output` config line, the Neural Monkey creates the directory `experiments/training` with these files:

- `git_commit` - the Git hash of the current Neural Monkey revision.
- `git_diff` - the diff between the clean checkout and the working copy.
- `experiment.ini` - the INI file used for running the training (a simple copy of the file NM was started with).
- `experiment.log` - the output log of the training script.
- `checkpoint` - file created by Tensorflow, keeps track of saved variables.
- `events.out.tfevents.<TIME>.<HOST>` - file created by Tensorflow, keeps the summaries for TensorBoard visualisation
- `variables.data[.<N>]` - a set of files with N best saved models.
- `variables.data.best` - a symbolic link that points to the variable file with the best model.

1.3.6 Part VI. - Evaluation of the Trained Model

If you have reached this point, you have nearly everything this tutorial offers. The last step of this tutorial is to take the trained model and to apply it to a previously unseen dataset. For this you will need two additional configuration files. But fear not - it's not going to be that difficult. The first configuration file is the specification of the model. We have this from Part III and a small optional change is needed. The second configuration file tells the run script which datasets to process.

The optional change of the model INI file prevents the training dataset from loading. This is a flaw in the present design and it is planned to change. The procedure is simple:

1. Copy the file `post-edit.ini` into e.g. `post-edit.test.ini`
2. Open the `post-edit.test.ini` file and remove the `train_dataset` and `val_dataset` sections, as well as the `train_dataset` and `val_dataset` configuration from the `[main]` section.

Now we have to make another file specifying the testing dataset configuration. We will call this file `post-edit_run.ini`:

```
[main]
test_datasets=[<eval_data>]
```

```
[eval_data]
class=dataset.load_dataset_from_files
s_source="exp-nm-ape/data/test/test.src"
s_translated="exp-nm-ape/data/test/test.mt"
s_greedy_edits_out="exp-nm-ape/test_output.edits"
```

The dataset specifies the two input series `s_source` and `s_translated` (the candidate MT output output to be post-edited) as in the training. The series `s_edits` (containing reference edits) is **not** present in the evaluation dataset, because we do not want to use the reference edits to compute loss at this point. Usually, we don't even *know* the correct output at runtime.

Instead, we introduce the output series `s_greedy_edits_out` (the prefix `s_` and the suffix `_out` are hardcoded in Neural Monkey and the series name in between has to match the name of the series produced by the runner).

The line `s_greedy_edits_out=` specifies the file where the output should be saved. (You may want to alter the path to the `exp-nm-ape` directory if it is not located inside the Neural Monkey package root dir.)

We have all that we need to run the trained model on the evaluation dataset. From the root directory of the Neural Monkey repository, run:

```
bin/neuralmonkey-run exp-nm-ape/post-edit.test.ini exp-nm-ape/post-edit_run.ini
```

At the end, you should see a new file `exp-nm-ape/test_output.edits`. As you notice, the contents of this file are the sequences of edit operations, which if applied to the machine translated sentences, generate the output that we want. The final step is to call the provided post-processing script. Again, feel free to write your own as a simple exercise:

```
scripts/postedit_reconstruct_data.py \
  --edits=exp-nm-ape/test_output.edits \
  --translated-sentences=exp-nm-ape/data/test/test.mt \
  > test_output.pe
```

Now, you can run the official tools (like `mteval` or the `tercom` software available on the [WMT 16 website](#)) to measure the score of `test_output.pe` on the `data/test/test.pe` reference evaluation dataset.

1.3.7 Part VII. - Conclusions

This tutorial gave you the basic overview of how to design your experiments using Neural Monkey. The sample experiment was the task of automatic post-editing. We got the data from the WMT 16 APE shared task and pre-processed them to fit our needs. We have written the configuration file and run the training. At the end, we evaluated the model on the test dataset.

If you want to learn more, the next step is perhaps to browse the `examples` directory in Neural Monkey repository and see some further possible setups. If you are planning to just design an experiment using existing modules, you can start by editing one of those examples as well.

If you want to dig in the code, you can browse the [repository](#). Please feel free to fork the repository and to send us pull requests. The [API documentation](#) is currently under construction, but it already contains a little information about Neural Monkey objects and their configuration options.

Have fun!

1.4 Machine Translation Tutorial

This tutorial will guide you through designing Machine Translation experiments in Neural Monkey. We assume that you already read *the post-editing tutorial*.

The goal of the translation task is to translate sentences from one language into another. For this tutorial we use data from the WMT 16 IT-domain translation shared task on English-to-Czech direction.

WMT is an annual machine translation conference where academic groups compete in translating different datasets over various language pairs.

1.4.1 Part I. - The Data

We are going to use the data for the WMT 16 IT-domain translation shared task. You can get them at the [WMT IT Translation Shared Task webpage](#) and there download Batch1 and Batch2 answers and Batch3 as a testing set. Or directly [here](#) and [testset](#).

Note: In this tutorial we are using only small dataset as an example, which is not big enough for real-life machine translation training.

We find several files for different languages in the downloaded archive. From which we use only the following files as our training, validation and test set:

1. ``Batch1a_cs.txt and Batch1a_en.txt`` as our Training set
2. ``Batch2a_cs.txt and Batch2a_en.txt`` as a Validation set
3. ``Batch3a_en.txt`` as a Test set

Now - before we start, let's make our experiment directory, in which we place all our work. Let's call it `exp-nm-mt`.

First extract all the downloaded files, then make gzip files from individual files and put arrange them into the following directory structure:

```
exp-nm-mt
|
\== data
  |
  |== train
  | |
  | |== Batch1a_en.txt.gz
  | | \== Batch1a_cs.txt.gz
  |
  |== dev
  | |
  | |== Batch2a_en.txt.gz
  | | \== Batch2a_cs.txt.gz
  |
  \== test
  |
  |== Batch3a_en.txt.gz
```

The gzipping is not necessary, if you put the dataset there in plaintext, it will work the same way. Neural Monkey recognizes gzipped files by their MIME

type and chooses the correct way to open them.

TODO The dataset is not tokenized and need to be preprocessed.

Byte Pair Encoding

Neural machine translation (NMT) models typically operate with a fixed vocabulary, but translation is an open-vocabulary problem. Byte pair encoding (BPE) enables NMT model translation on open-vocabulary by encoding rare and unknown words as sequences of subword units. This is based on an intuition that various word classes are translatable via smaller units than words. More information in the paper <https://arxiv.org/abs/1508.07909> BPE creates a list of merges that are used for splitting out-of-vocabulary words. Example of such splitting:

```
basketball => basket@@ ball
```

Postprocessing can be manually done by:

```
sed "s/@@ //g"
```

but Neural Monkey manages it for you.

BPE Generation

In order to use BPE, you must first generate *merge_file*, over all data. This file is generated on both source and target dataset. You can generate it by running following script:

```
neuralmonkey/lib/subword_nmt/learn_bpe.py -s 50000 < DATA > merge_file.bpe
```

With the data from this tutorial it would be the following command:

```
paste Batch1a_en.txt Batch1a_cs.txt \  
| neuralmonkey/lib/subword_nmt/learn_bpe.py -s 8000 \  
> exp-nm-mt/data/merge_file.bpe
```

You can change number of merges, this number is equivalent to the size of the vocabulary. Do not forget that as an input is the file containing both source and target sides.

1.4.2 Part II. - The Model Configuration

In this section, we create the configuration file `translation.ini` needed for the machine translation training. We mention only the differences from the main post-editing tutorial.

1 - Datasets

For training, we prepare two datasets. Since we are using BPE, we need to define the preprocessor. The configuration of the datasets looks like this:

```
[train_data]
class=dataset.load_dataset_from_files
s_source="exp-nm-mt/data/train/Batch1a_en.txt.gz"
s_target="exp-nm-mt/data/train/Batch1a_cs.txt.gz"
preprocessors=[("source", "source_bpe", <bpe_preprocess>), ("target", "target_bpe",
↪<bpe_preprocess>)]

[val_data]
class=dataset.load_dataset_from_files
s_source="exp-nm-mt/data/dev/Batch2a_en.txt.gz"
s_target="exp-nm-mt/data/dev/Batch2a_cs.txt.gz"
preprocessors=[("source", "source_bpe", <bpe_preprocess>), ("target", "target_bpe",
↪<bpe_preprocess>)]
```

2 - Preprocessor and Postprocessor

We need to tell the Neural Monkey how it should handle preprocessing and postprocessing due to the BPE:

```
[bpe_preprocess]
class=processors.bpe.BPEPreprocessor
merge_file="exp-nm-mt/data/merge_file.bpe"

[bpe_postprocess]
class=processors.bpe.BPEPostprocessor
```

3 - Vocabularies

For both encoder and decoder we use shared vocabulary created from BPE merges:

```
[shared_vocabulary]
class=vocabulary.from_bpe
path="exp-nm-mt/data/merge_file.bpe"
```

4 - Encoder and Decoder

The encoder and decoder are similar to those from *the post-editing tutorial*:

```
[encoder]
class=encoders.recurrent.SentenceEncoder
name="sentence_encoder"
rnn_size=300
max_input_len=50
embedding_size=300
dropout_keep_prob=0.8
attention_type=decoding_function.Attention
data_id="source_bpe"
vocabulary=<shared_vocabulary>

[decoder]
class=decoders.decoder.Decoder
name="decoder"
encoders=[<encoder>]
rnn_size=256
embedding_size=300
dropout_keep_prob=0.8
use_attention=True
data_id="target_bpe"
vocabulary=<shared_vocabulary>
max_output_len=50
```

You can notice that both encoder and decoder uses as input data id the data preprocessed by *<bpe_preprocess>*.

5 - Training Sections

The following sections are described in more detail in *the post-editing tutorial*:

```

[trainer]
class=trainers.cross_entropy_trainer.CrossEntropyTrainer
decoders=[<decoder>]
l2_weight=1.0e-8

[runner]
class=runners.runner.GreedyRunner
decoder=<decoder>
output_series="series_named_greedy"
postprocess=<bpe_postprocess>

[bleu]
class=evaluators.bleu.BLEUEvaluator
name="BLEU-4"

[tf_manager]
class=tf_manager.TensorFlowManager
num_threads=4
num_sessions=1
minimize_metric=False
save_n_best=3

```

As for the main configuration section do not forget to add BPE postprocessing:

```

[main]
name="machine translation"
output="exp-nm-mt/out-example-translation"
runners=[<runner>]
tf_manager=<tf_manager>
trainer=<trainer>
train_dataset=<train_data>
val_dataset=<val_data>
evaluation=[("series_named_greedy", "target", <bleu>), ("series_named_greedy", "target
↔", evaluators.ter.TER)]
batch_size=80
runners_batch_size=256
epochs=10
validation_period=5000
logging_period=80

```

1.4.3 Part III. - Running and Evaluation of the Experiment

1 - Training

The training can be run as simply as:

```
bin/neuralmonkey-train exp-nm-mt/translation.ini
```

2 - Resuming Training

If training stopped and you want to resume it, you can load pre-trained parameters by specifying the `initial_variables` of the model in the `[main]` section:

```
[main]
initial_variables=/path/to/variables.data
```

Note there is actually no file called `variables.data`, but three files with this common prefix. The `initial_variables` config value should correspond to this prefix.

3 - Evaluation

As for the evaluation, you need to create `translation_run.ini`:

```
[main]
test_datasets=[<eval_data>]
; We saved 3 models (save_n_best=3), so there are
; multiple models we could to translate with.
; We can go with the best model, or select one manually:
;variables=["exp-nm-mt/out-example-translation/variables.data.0"]

[bpe_preprocess]
class=processors.bpe.BPEPreprocessor
merge_file="exp-nm-mt/data/merge_file.bpe"

[eval_data]
class=dataset.load_dataset_from_files
s_source="exp-nm-mt/data/test/Batch3a_en.txt.gz"
s_series_named_greedy_out="exp-nm-mt/out-example-translation/evaluation.txt.out"
preprocessors=["source", "source_bpe", <bpe_preprocess>]
```

and run:

```
bin/neuralmonkey-run exp-nm-mt/translation.ini exp-nm-mt/translation_run.ini
```

You are ready to experiment with your own models.

1.5 Configuration

Experiments with NeuralMonkey are configured using configuration files which specifies the architecture of the model, meta-parameters of the learning, the data, the way the data are processed and the way the model is run.

1.5.1 Syntax

The configuration files are based on the syntax of INI files, see e.g., the corresponding [Wikipedia page](#)..

Neural Monkey INI files contain *key-value pairs*, delimited by an equal sign (=) with no spaces around. The key-value pairs are grouped into *sections* (Neural Monkey requires all pairs to belong to a section.)

Every section starts with its header which consists of the section name in square brackets. Everything below the header is considered a part of the section.

Comments can appear on their own (otherwise empty) line, prefixed either with a hash sign (#) or a semicolon (;) and possibly indented.

The configuration introduces several additional constructs for the values. There are both atomic values, and compound values.

Supported atomic values are:

- booleans: literals `True` and `False`
- integers: strings that could be interpreted as integers by Python (e.g., `1`, `002`)
- floats: strings that could be interpreted as floats by Python (e.g., `1.0`, `.123`, `2.`, `2.34e-12`)
- strings: string literals in quotes (e.g., `"walrus"`, `"5"`)
- section references: string literals in angle brackets (e.g., `<encoder>`), sections are later interpreted as Python objects
- Python names: strings without quotes which are neither booleans, integers and floats, nor section references (e.g., `neuralmonkey.encoders.SentenceEncoder`)

On top of that, there are two compound types syntax from Python:

- lists: comma-separated in squared brackets (e.g., `[1, 2, 3]`)
- tuples: comma-separated in round brackets (e.g., `("target", <ter>)`)

1.5.2 Interpretation

Each configuration file contains a `[main]` section which is interpreted as a dictionary having keys specified in the section and values which are results of interpretation of the right hand sides.

Both the atomic and compound types taken from Python (i.e., everything except the section references) are interpreted as their Python counterparts. (So if you write `42`, Neural Monkey actually sees `42`.)

Section references are interpreted as references to objects constructed when interpreting the referenced section. (So if you write `<session_manager>` in a right-hand side and a section `[session_manager]` later in the file, Neural Monkey will construct a Python object based on the key-value pairs in the section `[session_manager]`.)

Every section except the `[main]` section needs to contain the key `class` with a value of Python name which is a callable (e.g., a class constructor or a function). The other keys are used as named arguments of the callable.

1.5.3 Session Manager

This and following sections describes TensorFlow Manager from the users' perspective: what can be configured in Neural Monkey with respect to TensorFlow. The configuration of the TensorFlow manager is specified within the INI file in section with class `neuralmonkey.tf_manager.TensorFlowManager`:

```
[session_manager]
class=tf_manager.TensorFlowManager
...
```

The `session_manager` configuration object is then referenced from the main section of the configuration:

```
[main]
tf_manager=<session_manager>
...
```

1.5.4 Training on GPU

You can easily switch between CPU and GPU version by running your experiments in virtual environment containing either CPU or GPU version of TensorFlow without any changes to config files.

Similarly, standard techniques like setting the environment variable `CUDA_VISIBLE_DEVICES` can be used to control which GPUs are accessible for Neural Monkey.

By default, Neural Monkey prefers to allocate GPU memory stepwise only as needed. This can create problems with memory fragmentation. If you know that you can allocate the whole memory at once add the following parameter the `session_manager` section:

```
gpu_allow_growth=False
```

You can also restrict TensorFlow to use only a fixed proportion of GPU memory:

```
per_process_gpu_memory_fraction=0.65
```

This parameter tells TensorFlow to use only 65% of GPU memory.

With the default `gpu_allow_growth=True`, it makes sense to monitor memory consumption. Neural Monkey can include a short summary total GPU memory used in the periodic log line. Just set:

```
report_gpu_memory_consumption=True
```

The log line will then contain the information like: `MiB:0:7971/8113,1:4283/8113`. This particular message means that there are two GPU cards and the one indexed 1 has 4283 out of the total 8113 MiB occupied. Note that the information reports all GPUs on the machine, regardless `CUDA_VISIBLE_DEVICES`.

1.5.5 Training on CPUs

TensorFlow Manager settings also affect training on CPUs.

The line:

```
num_threads=4
```

indicates that 4 CPUs should be used for TensorFlow computations.

1.6 API Documentation

1.6.1 neuralmonkey package

The neuralmonkey package is the root package of this project.

Sub-modules

neuralmonkey

neuralmonkey package

Subpackages

neuralmonkey.attention package

Submodules

neuralmonkey.attention.base_attention module

Decoding functions using multiple attentions for RNN decoders.

See <http://arxiv.org/abs/1606.07481>

The attention mechanisms used in Neural Monkey are inherited from the `BaseAttention` class defined in this module.

Each attention object has the `attention` function which operates on the `attention_states` tensor. The attention function receives the query tensor, the decoder previous state and input, and its inner state, which could bear an arbitrary structure of information. The default structure for this is the `AttentionLoopState`, which contains a growing array of attention distributions and context vectors in time. That's why there is the `initial_loop_state` function in the `BaseAttention` class.

Mainly for illustration purposes, the attention objects can keep their *histories*, which is a dictionary populated with attention distributions in time for every decoder, that used this attention object. This is because for example the recurrent decoder is can be run twice for each sentence - once in the *training* mode, in which the decoder gets the reference tokens on the input, and once in the *running* mode, in which it gets its own outputs. The histories object is constructed *after* the decoding and its construction should be triggered manually from the decoder by calling the `finalize_loop` method.

```
class neuralmonkey.attention.base_attention.AttentionLoopState (contexts, weights)
```

```
    Bases: tuple
```

```
    contexts
```

```
        Alias for field number 0
```

```
    weights
```

```
        Alias for field number 1
```

```
class neuralmonkey.attention.base_attention.BaseAttention (name: str,  
                                                         save_checkpoint: str =  
                                                         None, load_checkpoint: str  
                                                         = None) → None
```

```
    Bases: neuralmonkey.model.model_part.ModelPart
```

```
    attention (query: tensorflow.python.framework.ops.Tensor, decoder_prev_state:  
              tensorflow.python.framework.ops.Tensor, decoder_input: ten-  
              sorflow.python.framework.ops.Tensor, loop_state: typing.Any,  
              step: tensorflow.python.framework.ops.Tensor) → typ-  
              ing.Tuple[tensorflow.python.framework.ops.Tensor, typing.Any]
```

```
        Get context vector for a given query.
```

```
    context_vector_size
```

```
    feed_dict (dataset: neuralmonkey.dataset.Dataset, train: bool = False) → typ-  
              ing.Dict[tensorflow.python.framework.ops.Tensor, typing.Any]
```

finalize_loop (*key: str, last_loop_state: typing.Any*) → None

histories

initial_loop_state () → typing.Any
Get initial loop state for the attention object.

visualize_attention (*key: str*) → None

neuralmonkey.attention.base_attention.**empty_attention_loop_state** () → neuralmonkey.attention.base_attention.AttentionLoopState

Create an empty attention loop state.

The attention loop state is a technical object for storing the attention distributions and the context vectors in time. It is used with the `tf.while_loop` dynamic implementation of the decoder.

This function returns an empty attention loop state which means there are two empty arrays, one for attention distributions in time, and one for the attention context vectors in time.

neuralmonkey.attention.base_attention.**get_attention_mask** (*encoder: typing.Union[neuralmonkey.model.stateful.TemporalStateful, neuralmonkey.model.stateful.SpatialStateful]*) → typing.Union[tensorflow.python.framework.ops.Tensor, NoneType]

neuralmonkey.attention.base_attention.**get_attention_states** (*encoder: typing.Union[neuralmonkey.model.stateful.TemporalStateful, neuralmonkey.model.stateful.SpatialStateful]*) → tensorflow.python.framework.ops.Tensor

neuralmonkey.attention.combination module

Attention combination strategies.

This module implements attention combination strategies for multi-encoder scenario when we may want to combine the hidden states of the encoders in more complicated fashion.

Currently there are two attention combination strategies flat and hierarchical (see paper [Attention Combination Strategies for Multi-Source Sequence-to-Sequence Learning](#)).

The combination strategies may use the sentinel mechanism which allows the decoder not to attend to the, and extract information on its own hidden state (see paper [Knowing when to Look: Adaptive Attention via a Visual Sentinel for Image Captioning](#)).

```

class neuralmonkey.attention.combination.FlatMultiAttention (name: str, encoders: typing.List[typing.Union[neuralmonkey.model.stateful.SpatialStateful]], attention_state_size: int, share_attn_projections: bool = False, use_sentinels: bool = False, save_checkpoint: str = None, load_checkpoint: str = None) → None

```

Bases: `neuralmonkey.attention.combination.MultiAttention`

Flat attention combination strategy.

Using this attention combination strategy, hidden states of the encoders are first projected to the same space (different projection for different encoders) and then we compute a joint distribution over all the hidden states. The context vector is then a weighted sum of another / then projection of the encoders hidden states. The sentinel vector can be added as an additional hidden state.

See equations 8 to 10 in the Attention Combination Strategies paper.

```

attention (query: tensorflow.python.framework.ops.Tensor, decoder_prev_state: tensorflow.python.framework.ops.Tensor, decoder_input: tensorflow.python.framework.ops.Tensor, loop_state: neuralmonkey.attention.base_attention.AttentionLoopState, step: tensorflow.python.framework.ops.Tensor) → typing.Tuple[tensorflow.python.framework.ops.Tensor, neuralmonkey.attention.base_attention.AttentionLoopState]

```

context_vector_size

```

finalize_loop (key: str, last_loop_state: neuralmonkey.attention.base_attention.AttentionLoopState) → None

```

get_encoder_projections (*scope*)

initial_loop_state () → `neuralmonkey.attention.base_attention.AttentionLoopState`

```

class neuralmonkey.attention.combination.HierarchicalLoopState (child_loop_states, loop_state)

```

Bases: `tuple`

child_loop_states

Alias for field number 0

loop_state

Alias for field number 1

```

class neuralmonkey.attention.combination.HierarchicalMultiAttention (name:
                                                                    str,  atten-
                                                                    tions:  typ-
                                                                    ing.List[neuralmonkey.attention.base
                                                                    atten-
                                                                    tion_state_size:
                                                                    int,
                                                                    use_sentinels:
                                                                    bool,
                                                                    share_attn_projections:
                                                                    bool,
                                                                    save_checkpoint:
                                                                    str = None,
                                                                    load_checkpoint:
                                                                    str = None)
                                                                    → None

```

Bases: *neuralmonkey.attention.combination.MultiAttention*

Hierarchical attention combination.

Hierarchical attention combination strategy first computes the context vector for each encoder separately using whatever attention type the encoders have. After that it computes a second attention over the resulting context vectors and optionally the sentinel vector.

See equations 6 and 7 in the Attention Combination Strategies paper.

```

attention (query: tensorflow.python.framework.ops.Tensor, decoder_prev_state:
tensorflow.python.framework.ops.Tensor, decoder_input: tensorflow.python.framework.ops.Tensor,
loop_state: neuralmonkey.attention.combination.HierarchicalLoopState, step: tensorflow.python.framework.ops.Tensor)
→ typing.Tuple[tensorflow.python.framework.ops.Tensor, neuralmonkey.attention.combination.HierarchicalLoopState]

```

context_vector_size

finalize_loop (key: str, last_loop_state: typing.Any) → None

initial_loop_state () → neuralmonkey.attention.combination.HierarchicalLoopState

```

class neuralmonkey.attention.combination.MultiAttention (name: str, atten-
                                                                    tion_state_size: int,
                                                                    share_attn_projections: bool
                                                                    = False, use_sentinels: bool =
                                                                    False, save_checkpoint: str =
                                                                    None, load_checkpoint: str =
                                                                    None) → None

```

Bases: *neuralmonkey.attention.base_attention.BaseAttention*

Base class for attention combination.

```

attention (query: tensorflow.python.framework.ops.Tensor, decoder_prev_state:
tensorflow.python.framework.ops.Tensor, decoder_input: tensorflow.python.framework.ops.Tensor,
loop_state: typing.Any, step: tensorflow.python.framework.ops.Tensor)
→ typing.Tuple[tensorflow.python.framework.ops.Tensor, typing.Any]

```

Get context vector for given decoder state.

attn_size

neuralmonkey.attention.coverage module

Coverage attention introduced in Tu et al. (2016).

See arxiv.org/abs/1601.04811

The CoverageAttention class inherits from the basic feed-forward attention introduced by Bahdanau et al. (2015)

```

class neuralmonkey.attention.coverage.CoverageAttention (name: str, encoder: typing.Union[neuralmonkey.model.stateful.TemporalStateful, neuralmonkey.model.stateful.SpatialStateful], dropout_keep_prob: float = 1.0, state_size: int = None, max_fertility: int = 5, save_checkpoint: str = None, load_checkpoint: str = None) → None

Bases: neuralmonkey.attention.feed_forward.Attention

get_energies (y: tensorflow.python.framework.ops.Tensor, weights_in_time: tensorflow.python.ops.tensor_array_ops.TensorArray)

```

neuralmonkey.attention.feed_forward module

The feed-forward attention mechanism.

This is the attention mechanism used in Bahdanau et al. (2015)

See arxiv.org/abs/1409.0473

```

class neuralmonkey.attention.feed_forward.Attention (name: str, encoder: typing.Union[neuralmonkey.model.stateful.TemporalStateful, neuralmonkey.model.stateful.SpatialStateful], dropout_keep_prob: float = 1.0, state_size: int = None, save_checkpoint: str = None, load_checkpoint: str = None) → None

Bases: neuralmonkey.attention.base_attention.BaseAttention

attention (query: tensorflow.python.framework.ops.Tensor, decoder_prev_state: tensorflow.python.framework.ops.Tensor, decoder_input: tensorflow.python.framework.ops.Tensor, loop_state: neuralmonkey.attention.base_attention.AttentionLoopState, step: tensorflow.python.framework.ops.Tensor) → typing.Tuple[tensorflow.python.framework.ops.Tensor, neuralmonkey.attention.base_attention.AttentionLoopState]

attention_mask

attention_states

bias_term

context_vector_size

finalize_loop (key: str, last_loop_state: neuralmonkey.attention.base_attention.AttentionLoopState) → None

get_energies (y, _)

```

```

hidden_features
initial_loop_state() → neuralmonkey.attention.base_attention.AttentionLoopState
key_projection_matrix
projection_bias_vector
query_projection_matrix
similarity_bias_vector
state_size

```

neuralmonkey.attention.scaled_dot_product module

The scaled dot-product attention mechanism defined in Vaswani et al. (2017).

The attention energies are computed as dot products between the query vector and the key vector. The query vector is scaled down by the square root of its dimensionality. This attention function has no trainable parameters.

See arxiv.org/abs/1706.03762

```

class neuralmonkey.attention.scaled_dot_product.MultiHeadAttention (name: str,
                                                                    n_heads: int,
                                                                    keys_encoder:
                                                                    typing.Union[neuralmonkey.model.stateful.
                                                                    neural-
                                                                    monkey.model.stateful.SpatialStateful]
                                                                    val-
                                                                    ues_encoder:
                                                                    typ-
                                                                    ing.Union[neuralmonkey.model.stateful.
                                                                    neural-
                                                                    monkey.model.stateful.SpatialStateful]
                                                                    = None,
                                                                    dropout_keep_prob:
                                                                    float = 1.0,
                                                                    save_checkpoint:
                                                                    str = None,
                                                                    load_checkpoint:
                                                                    str = None)
                                                                    → None

```

Bases: `neuralmonkey.attention.base_attention.BaseAttention`

```

attention (query: tensorflow.python.framework.ops.Tensor, decoder_prev_state:
              tensorflow.python.framework.ops.Tensor, decoder_input: tensorflow.python.framework.ops.Tensor,
              tensorflow.python.framework.ops.Tensor, loop_state: neuralmonkey.attention.scaled_dot_product.MultiHeadLoopStateTA,
              step: tensorflow.python.framework.ops.Tensor) → typing.Tuple[tensorflow.python.framework.ops.Tensor,
              neuralmonkey.attention.scaled_dot_product.MultiHeadLoopStateTA]

```

```

attention_single_head (query: tensorflow.python.framework.ops.Tensor,
                       keys: tensorflow.python.framework.ops.Tensor, val-
                       ues: tensorflow.python.framework.ops.Tensor) → typ-
                       ing.Tuple[tensorflow.python.framework.ops.Tensor,
                       tensorflow.python.framework.ops.Tensor]

```

```

context_vector_size
finalize_loop (key: str, last_loop_state: neuralmonkey.attention.scaled_dot_product.MultiHeadLoopStateTA)
    → None
initial_loop_state () → neuralmonkey.attention.scaled_dot_product.MultiHeadLoopStateTA
visualize_attention (key: str) → None
class neuralmonkey.attention.scaled_dot_product.MultiHeadLoopStateTA (contexts,
                                                                    head_weights)
    Bases: tuple
    contexts
        Alias for field number 0
    head_weights
        Alias for field number 1
class neuralmonkey.attention.scaled_dot_product.ScaledDotProdAttention (name:
                                                                    str,
                                                                    keys_encoder:
                                                                    typing.Union[neuralmonkey.model.
                                                                    neural-
                                                                    monkey.model.stateful.SpatialSta
                                                                    val-
                                                                    ues_encoder:
                                                                    typing.Union[neuralmonkey.model.
                                                                    neural-
                                                                    monkey.model.stateful.SpatialSta
                                                                    = None,
                                                                    dropout_keep_prob:
                                                                    float
                                                                    = 1.0,
                                                                    save_checkpoint:
                                                                    str =
                                                                    None,
                                                                    load_checkpoint:
                                                                    str =
                                                                    None)
                                                                    →
                                                                    None
    Bases: neuralmonkey.attention.scaled_dot_product.MultiHeadAttention

```

Module contents

neuralmonkey.config package

Submodules

neuralmonkey.config.builder module

Configuration Object Builder.

This module is responsible for instantiating objects specified by the experiment configuration.

class `neuralmonkey.config.builder.ClassSymbol` (*string: str*) → None
Bases: object

Represents a class (or other callable) in configuration.

create () → typing.Any

class `neuralmonkey.config.builder.ObjectRef` (*expression: str*) → None
Bases: object

Represents a named object or its attribute in configuration.

bind (*value: typing.Any*)

target

`neuralmonkey.config.builder.build_config` (*config_dicts: typing.Dict[str, typing.Any]*, *ignore_names: typing.Set[str]*, *warn_unused: bool = False*) → typing.Dict[str, typing.Any]

Build the model from the configuration.

Parameters

- **config_dicts** – The parsed configuration file
- **ignore_names** – A set of names that should be ignored during the loading.
- **warn_unused** – Emit a warning if there are unused sections.

`neuralmonkey.config.builder.build_object` (*value: str*, *all_dicts: typing.Dict[str, typing.Any]*, *existing_objects: typing.Dict[str, typing.Any]*, *depth: int*) → typing.Any

Build an object from config dictionary of its arguments.

Works recursively.

Parameters

- **value** – Value that should be resolved (either a literal value or a config section name)
- **all_dicts** – Configuration dictionaries used to find configuration of unconstructed objects.
- **existing_objects** – Dictionary of already constructed objects.
- **ignore_names** – Set of names that should be ignored.
- **depth** – The current depth of recursion. Used to prevent an infinite
- **recursion.** –

`neuralmonkey.config.builder.instantiate_class` (*name: str*, *all_dicts: typing.Dict[str, typing.Any]*, *existing_objects: typing.Dict[str, typing.Any]*, *depth: int*) → typing.Any

Instantiate a class from the configuration.

Arguments: see `help(build_object)`

neuralmonkey.config.configuration module

class `neuralmonkey.config.configuration.Configuration`
Bases: object

Configuration loader.

Loads the configuration file in an analogical way the python's `argparse.ArgumentParser` works.

add_argument (*name: str, required: bool = False, default: typing.Any = None, cond: typing.Callable[[typing.Any], bool] = None*) → None

build_model (*warn_unused=False*) → None

ignore_argument (*name: str*) → None

load_file (*path: str, changes: typing.Union[typing.List[str], NoneType] = None*) → None

make_namespace (*d_obj*) → `argparse.Namespace`

save_file (*path: str*) → None

neuralmonkey.config.exceptions module

Module that contains exceptions handled in config parsing and loading.

exception `neuralmonkey.config.exceptions.ConfigBuildException` (*object_name: str, original_exception: Exception*) → None

Bases: `Exception`

Exception caused by error in loading the model.

exception `neuralmonkey.config.exceptions.ConfigInvalidValueException` (*value: typing.Any, message: str*) → None

Bases: `Exception`

exception `neuralmonkey.config.exceptions.IniError` (*line: int, message: str, original_exc: typing.Union[Exception, NoneType] = None*) → None

Bases: `Exception`

Exception caused by error in INI file syntax.

neuralmonkey.config.parsing module

Module responsible for INI parsing.

`neuralmonkey.config.parsing.parse_file` (*config_file: typing.Iterable[str], changes: typing.Union[typing.Iterable[str], NoneType] = None*) → `typing.Tuple[typing.Dict[str, typing.Any], typing.Dict[str, typing.Any]]`

Parse an INI file and creates all values.

`neuralmonkey.config.parsing.write_file` (*config_dict: typing.Dict[str, typing.Any], config_file: typing.IO[str]*) → None

neuralmonkey.config.utils module

Utilities.

This module contains helper functions that are supposed to be called from the configuration file because calling the functions or the class constructors directly would be inconvenient or impossible.

```
neuralmonkey.config.utils.adadelat_optimizer (**kwargs) → tensor-  
flow.python.training.adadelat.AdadelatOptimizer  
neuralmonkey.config.utils.adam_optimizer (learning_rate: float = 0.0001) → tensor-  
flow.python.training.adam.AdamOptimizer  
neuralmonkey.config.utils.deprecated (func: typing.Callable[... , T]) → typing.Callable[... , T]  
neuralmonkey.config.utils.variable (initial_value=0, trainable: bool = False, **kwargs) →  
tensorflow.python.ops.variables.Variable
```

Module contents

neuralmonkey.decoders package

Submodules

neuralmonkey.decoders.beam_search_decoder module

Beam search decoder.

This module implements the beam search algorithm for the recurrent decoder.

As well as the recurrent decoder, this decoder works dynamically, which means it uses the `tf.while_loop` function conditioned on both maximum output length and list of finished hypotheses.

The beam search decoder works by appending data from `SearchStepOutput` objects to a `SearchStepOutputTA` object. The `SearchStepOutput` object stores information about the hypotheses in the beam. Each hypothesis keeps its score, its final token, and a pointer to a “parent” hypothesis, which is a one-token-shorter hypothesis which shares the tokens with the child hypothesis.

For the beam search decoder to work, it must keep an inner state which stores information about hypotheses in the beam. It is an object of type `SearchState` which stores, for each hypothesis, its sum of log probabilities of the tokens, its length, finished flag, ID of the last token, and the last decoder and attention states.

There is another inner state object here, the `BeamSearchLoopState`. It is a technical structure used with the `tf.while_loop` function. It stores all the previously mentioned information, plus the decoder `LoopState`, which is used in the decoder when its own `tf.while_loop` function is used - this is not the case when using beam search because we want to run the decoder’s steps manually.

```
class neuralmonkey.decoders.beam_search_decoder.BeamSearchDecoder (name: str, par-  
ent_decoder:  
neural-  
monkey.decoders.decoder.Decoder,  
beam_size: int,  
length_normalization:  
float,  
max_steps:  
int = None,  
save_checkpoint:  
str = None,  
load_checkpoint:  
str = None) →  
None
```

Bases: `neuralmonkey.model.model_part.ModelPart`

In-graph beam search for batch size 1.

The hypothesis scoring algorithm is taken from <https://arxiv.org/pdf/1609.08144.pdf>. Length normalization is parameter alpha from equation 14.

beam_size

feed_dict (*dataset: neuralmonkey.dataset.Dataset, train: bool = False*) → typing.Dict[*tensorflow.python.framework.ops.Tensor, typing.Any*]
Populate the feed dictionary for the decoder object.

Parameters

- **dataset** – The dataset to use for the decoder.
- **train** – Boolean flag, telling whether this is a training run

get_body () → typing.Callable
Return a body function for `tf.while_loop`.

get_initial_loop_state () → `neuralmonkey.decoders.beam_search_decoder.BeamSearchLoopState`

vocabulary

```
class neuralmonkey.decoders.beam_search_decoder.BeamSearchLoopState(bs_state,
                                                                    bs_output,
                                                                    de-
                                                                    coder_loop_state)
```

Bases: tuple

bs_output
Alias for field number 1

bs_state
Alias for field number 0

decoder_loop_state
Alias for field number 2

```
class neuralmonkey.decoders.beam_search_decoder.SearchState(logprob_sum, lengths,
                                                            finished, last_word_ids,
                                                            last_state, last_attns)
```

Bases: tuple

finished
Alias for field number 2

last_attns
Alias for field number 5

last_state
Alias for field number 4

last_word_ids
Alias for field number 3

lengths
Alias for field number 1

logprob_sum
Alias for field number 0

```
class neuralmonkey.decoders.beam_search_decoder.SearchStepOutput(scores, par-
                                                                    ent_ids, to-
                                                                    ken_ids)
```

Bases: tuple

parent_ids
Alias for field number 1

scores
Alias for field number 0

token_ids
Alias for field number 2

class `neuralmonkey.decoders.beam_search_decoder.SearchStepOutputTA` (*scores*, *parent_ids*, *token_ids*)

Bases: `tuple`

parent_ids
Alias for field number 1

scores
Alias for field number 0

token_ids
Alias for field number 2

neuralmonkey.decoders.classifier module

class `neuralmonkey.decoders.classifier.Classifier` (*name*: *str*; *encoders*: *typing.List[neuralmonkey.model.stateful.Stateful]*, *vocabulary*: *neuralmonkey.vocabulary.Vocabulary*, *data_id*: *str*; *layers*: *typing.List[int]*, *activation_fn*: *typing.Callable[[tensorflow.python.framework.ops.Tensor], tensorflow.python.framework.ops.Tensor]* = *<function relu>*, *dropout_keep_prob*: *float* = 0.5, *save_checkpoint*: *typing.Union[str, NoneType]* = *None*, *load_checkpoint*: *typing.Union[str, NoneType]* = *None*) → *None*

Bases: `neuralmonkey.model.model_part.ModelPart`

A simple MLP classifier over encoders.

The API pretends it is an RNN decoder which always generates a sequence of length exactly one.

cost

decoded

decoded_logits

decoded_seq

feed_dict (*dataset*: *neuralmonkey.dataset.Dataset*, *train*: *bool* = *False*) → *typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Any]*

gt_inputs

loss_with_decoded_ins

loss_with_gt_ins

`runtime_logprobs``runtime_loss``train_loss``train_mode`

neuralmonkey.decoders.ctc_decoder module

```
class neuralmonkey.decoders.ctc_decoder.CTCDecoder (name: str, encoder: typing.Any, vocabulary: neuralmonkey.vocabulary.Vocabulary, data_id: str, merge_repeated_targets: bool = False, merge_repeated_outputs: bool = True, beam_width: int = 1, save_checkpoint: typing.Union[str, NoneType] = None, load_checkpoint: typing.Union[str, NoneType] = None) → None
```

Bases: `neuralmonkey.model.model_part.ModelPart`

Connectionist Temporal Classification.

See `tf.nn.ctc_loss`, `tf.nn.ctc_greedy_decoder` etc.

`cost``decoded`

```
feed_dict (dataset: neuralmonkey.dataset.Dataset, train: bool = False) → typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Any]
```

`input_lengths``logits``runtime_loss``train_loss``train_mode``train_targets`

neuralmonkey.decoders.decoder module

```
class neuralmonkey.decoders.decoder.Decoder (encoders: typing.List[neuralmonkey.model.stateful.Stateful],
                                              vocabulary: neuralmonkey.vocabulary.Vocabulary, data_id: str,
                                              name: str, max_output_len: int, dropout_keep_prob: float = 1.0,
                                              rnn_size: int = None, embedding_size: int = None,
                                              output_projection: typing.Union[typing.Tuple[typing.Callable[[tensorflow.python.framework.ops.Tensor, tensorflow.python.framework.ops.Tensor], tensorflow.python.framework.ops.Tensor], tensorflow.python.framework.ops.Tensor], tensorflow.python.framework.ops.Tensor],
                                              int, typing.Callable[[tensorflow.python.framework.ops.Tensor, tensorflow.python.framework.ops.Tensor], tensorflow.python.framework.ops.Tensor],
                                              tensorflow.python.framework.ops.Tensor], tensorflow.python.framework.ops.Tensor]
                                              = None, encoder_projection: typing.Callable[[tensorflow.python.framework.ops.Tensor, int, typing.List[neuralmonkey.model.stateful.Stateful]], tensorflow.python.framework.ops.Tensor]
                                              = None, attentions: typing.List[neuralmonkey.attention.base_attention.BaseAttention]
                                              = None, embeddings_source: neuralmonkey.model.sequence.EmbeddedSequence
                                              = None, attention_on_input: bool = True, rnn_cell: str = 'GRU', conditional_gru: bool = False,
                                              save_checkpoint: str = None, load_checkpoint: str = None) → None
```

Bases: `neuralmonkey.model.model_part.ModelPart`

Decoder class.

A class that manages parts of the computation graph that are used for the decoding.

batch_size

cost

decoded

decoding_b

decoding_w

embed_input_symbol (*args) → tensorflow.python.framework.ops.Tensor

embedding_matrix

Variables and operations for embedding of input words.

If we are reusing word embeddings, this function takes the embedding matrix from the first encoder

feed_dict (dataset: neuralmonkey.dataset.Dataset, train: bool = False) → typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Any]

Populate the feed dictionary for the decoder object.

Parameters

- **dataset** – The dataset to use for the decoder.
- **train** – Boolean flag, telling whether this is a training run

get_body (*train_mode: bool, sample: bool = False*) → typing.Callable

get_initial_loop_state () → neuralmonkey.decoders.decoder.LoopState

go_symbols

initial_state

Compute initial decoder state.

The part of the computation graph that computes the initial state of the decoder.

input_plus_attention (*args) → tensorflow.python.framework.ops.Tensor

Merge input and previous attentions.

Input and previous attentions are merged into a single vector of the size fo embedding.

loop_continue_criterion (*args) → tensorflow.python.framework.ops.Tensor

runtime_logits

runtime_logprobs

runtime_loop_result

runtime_loss

runtime_mask

runtime_rnn_states

train_inputs

train_logits

train_logprobs

train_loss

train_mode

train_padding

train_xents

```
class neuralmonkey.decoders.decoder.LoopState (step, input_symbol, train_inputs,
                                              prev_rnn_state, prev_rnn_output,
                                              rnn_outputs, prev_logits, logits,
                                              prev_contexts, mask, finished, atten-
                                              tion_loop_states)
```

Bases: tuple

attention_loop_states

Alias for field number 11

finished

Alias for field number 10

input_symbol

Alias for field number 1

logits

Alias for field number 7

- mask**
Alias for field number 9
- prev_contexts**
Alias for field number 8
- prev_logits**
Alias for field number 6
- prev_rnn_output**
Alias for field number 4
- prev_rnn_state**
Alias for field number 3
- rnn_outputs**
Alias for field number 5
- step**
Alias for field number 0
- train_inputs**
Alias for field number 2

neuralmonkey.decoders.encoder_projection module

Encoder Projection Module.

This module contains different variants of projection of encoders into the initial state of the decoder.

Encoder projections are specified in the configuration file. Each encoder projection function has a unified type `EncoderProjection`, which is a callable that takes three arguments:

1. `train_mode` – boolean tensor specifying whether the train mode is on
2. `rnn_size` – the size of the resulting initial state
3. `encoders` – a list of `Stateful` objects used as the encoders.

To enable further parameterization of encoder projection functions, one can use higher-order functions.

`neuralmonkey.decoders.encoder_projection.concat_encoder_projection` (*train_mode*:

tensor-
flow.python.framework.ops.Tensor,
rnn_size:
int =
None,
encoders:
typ-
ing.List[neuralmonkey.model.statef
= None)
→ tensor-
flow.python.framework.ops.Tensor

Concatenate the encoded values of the encoders.

`neuralmonkey.decoders.encoder_projection.empty_initial_state` (*train_mode:*
tensor-
flow.python.framework.ops.Tensor,
rnn_size: int,
encoders: typing.List[neuralmonkey.model.stateful.Stateful
= None) → tensor-
flow.python.framework.ops.Tensor

Return an empty vector.

`neuralmonkey.decoders.encoder_projection.linear_encoder_projection` (*dropout_keep_prob:*
float)
→ typing.Callable[[tensorflow.python.frame
int, typing.List[neuralmonkey.model.state
tensorflow.python.framework.ops.Tensor]

Return a linear encoder projection.

Return a projection function which applies dropout on concatenated encoder final states and returns a linear projection to a `rnn_size`-sized tensor.

Parameters `dropout_keep_prob` – The dropout keep probability

`neuralmonkey.decoders.encoder_projection.nematus_projection` (*dropout_keep_prob:*
float = 1.0) → typing.Callable[[tensorflow.python.framework.op
int, typing.List[neuralmonkey.model.stateful.Stateful
tensorflow-
flow.python.framework.ops.Tensor]

Return encoder projection used in Nematus.

The initial state is a dense projection with tanh activation computed on the averaged states of the encoders. Dropout is applied to the means (before the projection).

Parameters `dropout_keep_prob` – The dropout keep probability.

neuralmonkey.decoders.output_projection module

Output Projection Module.

This module contains different variants of projection functions of decoder outputs into the logit function inputs.

Output projections are specified in the configuration file. Each output projection function has a unified type `OutputProjection`, which is a callable that takes four arguments and returns a tensor:

1. `prev_state` – the hidden state of the decoder.
2. `prev_output` – embedding of the previously decoded word (or train input)
3. `ctx_tensors` – a list of context vectors (for each attention object)

To enable further parameterization of output projection functions, one can use higher-order functions.

`neuralmonkey.decoders.output_projection.maxout_output` (*maxout_size: int*) → `typing.Tuple[typing.Callable[[tensorflow.python.framework.tensorflow.python.framework.ops.Tensor], tensorflow.python.framework.ops.Tensor], typing.List[tensorflow.python.framework.ops.Tensor], tensorflow.python.framework.ops.Tensor], tensorflow.python.framework.ops.Tensor], int]`

Apply maxout.

Compute RNN output out of the previous state and output, and the context tensors returned from attention mechanisms, as described in the article

This function corresponds to the equations for computation the $t_{\tilde{}}$ in the Bahdanau et al. (2015) paper, on page 14, with the maxout projection, before the last linear projection.

Parameters `maxout_size` – The size of the hidden maxout layer in the deep output

Returns Returns the maxout projection of the concatenated inputs

`neuralmonkey.decoders.output_projection.mlp_output` (*layer_sizes: typing.List[int], activation: typing.Callable[[tensorflow.python.framework.ops.Tensor], tensorflow.python.framework.ops.Tensor] = <function tanh>, dropout_keep_prob: float = 1.0*) → `typing.Tuple[typing.Callable[[tensorflow.python.framework.ops.Tensor], tensorflow.python.framework.ops.Tensor], typing.List[tensorflow.python.framework.ops.Tensor], tensorflow.python.framework.ops.Tensor], tensorflow.python.framework.ops.Tensor], int]`

Apply a multilayer perceptron.

Compute RNN deep output using the multilayer perceptron with a specified activation function. (Pascanu et al., 2013 [<https://arxiv.org/pdf/1312.6026v5.pdf>])

Parameters

- `layer_sizes` – A list of sizes of the hiddel layers of the MLP
- `dropout_keep_prob` – the dropout keep probability
- `activation` – The activation function to use in each layer.

```
neuralmonkey.decoders.output_projection.nematus_output (output_size:          int,
                                                         dropout_keep_prob:
                                                         float = 1.0) → typing.Tuple[typing.Callable[[tensorflow.python.framework.
                                                         tensorflow.
                                                         flow.python.framework.ops.Tensor,
                                                         typing.
                                                         List[tensorflow.python.framework.ops.Tensor],
                                                         tensorflow.
                                                         flow.python.framework.ops.Tensor],
                                                         tensorflow.
                                                         flow.python.framework.ops.Tensor],
                                                         int]
```

Apply nonlinear one-hidden-layer deep output.

Implementation consistent with Nematus. Can be used instead of (and is in theory equivalent to) `nonlinear_output`.

Projects the RNN state, embedding of the previously outputted word, and concatenation of all context vectors into a shared vector space, sums them up and apply a hyperbolic tangent activation function.

```
neuralmonkey.decoders.output_projection.nonlinear_output (output_size:          int,
                                                         activation_fn:          typing.Callable[[tensorflow.python.framework.ops.Tensor,
                                                         tensorflow.
                                                         flow.python.framework.ops.Tensor]
                                                         =
                                                         <function
                                                         tanh>]) → typing.Tuple[typing.Callable[[tensorflow.python.framework.
                                                         tensorflow.
                                                         flow.python.framework.ops.Tensor,
                                                         typing.
                                                         List[tensorflow.python.framework.ops.Tensor],
                                                         tensorflow.
                                                         flow.python.framework.ops.Tensor],
                                                         tensorflow.
                                                         flow.python.framework.ops.Tensor],
                                                         int]
```

neuralmonkey.decoders.sequence_labeler module

```

class neuralmonkey.decoders.sequence_labeler.SequenceLabeler (name: str, en-
coder: typing.Union[neuralmonkey.encoders.recurrent.RecurrentEncoder,
neural-
monkey.encoders.facebook_conv.SentenceEncoder],
vocabulary: neuralmonkey.vocabulary.Vocabulary,
data_id: str,
dropout_keep_prob: float = 1.0,
save_checkpoint: typing.Union[str,
NoneType] = None,
load_checkpoint: typing.Union[str,
NoneType] = None)
→ None

```

Bases: *neuralmonkey.model.model_part.ModelPart*

Classifier assing a label to each encoder's state.

cost

decoded

feed_dict (*dataset: neuralmonkey.dataset.Dataset, train: bool = False*) → *typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Any]*

logits

logprobs

runtime_loss

train_loss

train_mode

train_targets

train_weights

neuralmonkey.decoders.sequence_regressor module

```

class neuralmonkey.decoders.sequence_regressor.SequenceRegressor (name:      str,
                                                                encoders:  typing.List[neuralmonkey.model.stateful.StatefulModel],
                                                                data_id:   str,
                                                                layers:   typing.List[int]
                                                                = None,  activation_fn: typing.Callable[[tensorflow.python.framework.tensorflow.python.framework.ops.Tensor]
                                                                = <function relu>,
                                                                dropout_keep_prob: float = 1.0, dimension: int = 1,
                                                                save_checkpoint: str = None,
                                                                load_checkpoint: str = None) → None

```

Bases: *neuralmonkey.model.model_part.ModelPart*

A simple MLP regression over encoders.

The API pretends it is an RNN decoder which always generates a sequence of length exactly one.

cost

decoded

feed_dict (*dataset: neuralmonkey.dataset.Dataset, train: bool = False*) → typing.Dict[*tensorflow.python.framework.ops.Tensor, typing.Any*]

predictions

runtime_loss

train_inputs

train_loss

train_mode

neuralmonkey.decoders.word_alignment_decoder module

```
class neuralmonkey.decoders.word_alignment_decoder.WordAlignmentDecoder (encoder:
    neu-
    ral-
    monkey.encoders.recurrent.Rec-
    de-
    coder:
    neu-
    ral-
    monkey.decoders.decoder.Deco-
    data_id:
    str,
    name:
    str)
    →
    None
```

Bases: *neuralmonkey.model.model_part.ModelPart*

A decoder that computes soft alignment from an attentive encoder.

Loss is computed as cross-entropy against a reference alignment.

alignment_target

cost

feed_dict (*dataset:* *neuralmonkey.dataset.Dataset*, *train:* *bool* = *False*) → *typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Any]*

ref_alignment

Module contents

neuralmonkey.encoders package

Submodules

neuralmonkey.encoders.cnn_encoder module

CNN for image processing.

```
class neuralmonkey.encoders.cnn_encoder.CNNEncoder (name: str; data_id: str; convolu-
    tions: typing.List[typing.Tuple[int,
    int, typing.Union[int, NoneType]]],
    image_height: int, image_width:
    int, pixel_dim: int, fully_connected:
    typing.Union[typing.List[int], None-
    Type] = None, dropout_keep_prob:
    float = 0.5, save_checkpoint: typ-
    ing.Union[str, NoneType] = None,
    load_checkpoint: typing.Union[str,
    NoneType] = None) → None

Bases: neuralmonkey.model.model_part.ModelPart, neuralmonkey.model.stateful.
SpatialStatefulWithOutput
```

An image encoder.

It projects the input image through a serie of convoluitoal operations. The projected image is vertically cut and fed to stacked RNN layers which encode the image into a single vector.

feed_dict (*dataset:* *neuralmonkey.dataset.Dataset*, *train:* *bool = False*) → *typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Any]*

image_input

image_processing_layers

Do all convolutions and return the last conditional map.

Applies convolutions on the input tensor with optional max pooling. All the intermediate layers are stored in the *image_processing_layers* attribute. There is not dropout between the convolutional layers, by default the activation function is ReLU.

output

Output vector of the CNN.

If there are specified some fully connected layers, there are applied on top of the last convolutional map. Dropout is applied between all layers, default activation function is ReLU. There are only projection layers, no softmax is applied.

If there is fully_connected layer specified, average-pooled last convolutional map is used as a vector output.

spatial_mask

spatial_states

train_mode

neuralmonkey.encoders.facebook_conv module

From the paper Convolutional Sequence to Sequence Learning.

<http://arxiv.org/abs/1705.03122>

```
class neuralmonkey.encoders.facebook_conv.SentenceEncoder (name: str, input_sequence: neuralmonkey.model.sequence.EmbeddedSequence,
conv_features: int,
encoder_layers: int,
kernel_width: int = 5,
dropout_keep_prob: float = 1.0, save_checkpoint: str = None, load_checkpoint:
str = None) → None
```

Bases: *neuralmonkey.model.model_part.ModelPart*, *neuralmonkey.model.stateful.TemporalStatefulWithOutput*

feed_dict (*dataset:* *neuralmonkey.dataset.Dataset*, *train:* *bool = False*) → *typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Any]*

order_embeddings

ordered_embedded_inputs

output

temporal_mask

temporal_states

`train_mode`

neuralmonkey.encoders.imagenet_encoder module

Pre-trained ImageNet networks.

```
class neuralmonkey.encoders.imagenet_encoder.ImageNet (name: str, data_id: str, network_type: str, attention_layer: typing.Union[str, NoneType] = None, fine_tune: bool = False, encoded_layer: typing.Union[str, NoneType] = None, load_checkpoint: typing.Union[str, NoneType] = None, save_checkpoint: typing.Union[str, NoneType] = None) → None

Bases: neuralmonkey.model.model_part.ModelPart, neuralmonkey.model.stateful.SpatialStatefulWithOutput
```

Pre-trained ImageNet network.

HEIGHT = 224

WIDTH = 224

feed_dict (dataset: neuralmonkey.dataset.Dataset, train: bool = False) → typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Any]

input_image

output

spatial_mask

spatial_states

neuralmonkey.encoders.numpy_encoder module

```
class neuralmonkey.encoders.numpy_encoder.PostCNNImageEncoder (name: str, input_shape: typing.List[int], output_shape: int, data_id: str, save_checkpoint: typing.Union[str, NoneType] = None, load_checkpoint: typing.Union[str, NoneType] = None) → None

Bases: neuralmonkey.model.model_part.ModelPart, neuralmonkey.model.stateful.SpatialStatefulWithOutput
```

feed_dict (dataset: neuralmonkey.dataset.Dataset, train: bool = False) → typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Any]

output

spatial_mask**spatial_states**

class `neuralmonkey.encoders.numpy_encoder.VectorEncoder` (*name: str, dimension: int, data_id: str, output_shape: int = None, save_checkpoint: str = None, load_checkpoint: str = None*) → None

Bases: `neuralmonkey.model.model_part.ModelPart`, `neuralmonkey.model.stateful.Stateful`

feed_dict (*dataset: neuralmonkey.dataset.Dataset, train: bool = False*) → `typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Any]`

output

neuralmonkey.encoders.raw_rnn_encoder module

class `neuralmonkey.encoders.raw_rnn_encoder.RNNSpec` (*size, direction, cell_type*)

Bases: tuple

cell_type
Alias for field number 2

direction
Alias for field number 1

size
Alias for field number 0

class `neuralmonkey.encoders.raw_rnn_encoder.RawRNNEncoder` (*name: str, data_id: str, input_size: int, rnn_layers: typing.List[typing.Union[typing.Tuple[int], typing.Tuple[int, str], typing.Tuple[int, str, str]]], max_input_len: typing.Union[int, NoneType] = None, dropout_keep_prob: float = 1.0, save_checkpoint: typing.Union[str, NoneType] = None, load_checkpoint: typing.Union[str, NoneType] = None*) → None

Bases: `neuralmonkey.model.model_part.ModelPart`, `neuralmonkey.model.stateful.TemporalStatefulWithoutOutput`

A raw RNN encoder that gets input as a tensor.

feed_dict (*dataset: neuralmonkey.dataset.Dataset, train: bool = False*) → `typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Any]`
Populate the feed dictionary with the encoder inputs.

Parameters

- **dataset** – The dataset to use

- **train** – Boolean flag telling whether it is training time

output

temporal_mask

temporal_states

neuralmonkey.encoders.recurrent module

```
class neuralmonkey.encoders.recurrent.FactoredEncoder (name: str, vocabularies: typing.List[neuralmonkey.vocabulary.Vocabulary],
data_ids: typing.List[str], embedding_sizes: typing.List[int],
rnn_size: int, max_input_len: int = None, dropout_keep_prob: float = 1.0, rnn_cell: str = 'GRU', output_size: int = None,
save_checkpoint: str = None, load_checkpoint: str = None) → None
Bases: neuralmonkey.encoders.recurrent.RecurrentEncoder
```

```
class neuralmonkey.encoders.recurrent.RecurrentEncoder (name: str, input_sequence: neuralmonkey.model.sequence.Sequence,
rnn_size: int, dropout_keep_prob: float = 1.0, rnn_cell: str = 'GRU', output_size: int = None,
save_checkpoint: str = None, load_checkpoint: str = None) → None
Bases: neuralmonkey.model.model_part.ModelPart, neuralmonkey.model.stateful.TemporalStatefulWithOutput
```

bidirectional_rnn

```
feed_dict (dataset: neuralmonkey.dataset.Dataset, train: bool = False) → typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Any]
```

output

states

states_mask

temporal_mask

temporal_states

train_mode

```

class neuralmonkey.encoders.recurrent.SentenceEncoder (name: str, vocabulary: neural-
monkey.vocabulary.Vocabulary,
data_id: str, embedding_size:
int, rnn_size: int, max_input_len:
int = None, dropout_keep_prob:
float = 1.0, rnn_cell: str =
'GRU', output_size: int = None,
save_checkpoint: str = None,
load_checkpoint: str = None) →
None
Bases: neuralmonkey.encoders.recurrent.RecurrentEncoder

```

neuralmonkey.encoders.sentence_cnn_encoder module

Encoder for sentences without explicit segmentation.

```

class neuralmonkey.encoders.sentence_cnn_encoder.SentenceCNNEncoder (name:
str, input_sequence:
neural-
monkey.model.sequence.Sequence,
segment_size:
int, highway_depth:
int,
rnn_size:
int, filters: typ-
ing.List[typing.Tuple[int,
int]],
dropout_keep_prob:
float = 1.0,
use_noisy_activations:
bool =
False,
save_checkpoint:
typing.Union[str,
NoneType]
= None,
load_checkpoint:
typing.Union[str,
NoneType]
= None) →
None
Bases: neuralmonkey.model.model_part.ModelPart, neuralmonkey.model.stateful.
TemporalStatefulWithOutput

```

Recurrent over Convolutional Encoder.

Encoder processing a sentence using a CNN then running a bidirectional RNN on the result.

Based on: Jason Lee, Kyunghyun Cho, Thomas Hofmann: Fully Character-Level Neural Machine Translation without Explicit Segmentation.

See <https://arxiv.org/pdf/1610.03017.pdf>

bidirectional_rnn

cnn_encoded

1D convolution with max-pool that processing characters.

feed_dict (*dataset:* *neuralmonkey.dataset.Dataset*, *train:* *bool* = *False*) → *typing.Dict*[*tensorflow.python.framework.ops.Tensor*, *typing.Any*]
Populate the feed dictionary with the encoder inputs.

Parameters

- **dataset** – The dataset to use
- **train** – Boolean flag telling whether it is training time

highway_layer

Highway net projection following the CNN.

output

rnn_cells () → *typing.Tuple*[*tensorflow.python.ops.rnn_cell_impl.RNNCell*, *tensorflow.python.ops.rnn_cell_impl.RNNCell*]
Return the graph template to for creating RNN memory cells.

temporal_mask

temporal_states

train_mode

neuralmonkey.encoders.sequence_cnn_encoder module

Encoder for sentence classification with 1D convolutions and max-pooling.

```

class neuralmonkey.encoders.sequence_cnn_encoder.SequenceCNNEncoder (name: str,
                                                                    vocabulary:
                                                                    neural-
                                                                    monkey.vocabulary.Vocabulary,
                                                                    data_id: str,
                                                                    embed-
                                                                    ding_size:
                                                                    int,
                                                                    fil-
                                                                    ters: typ-
                                                                    ing.List[typing.Tuple[int,
                                                                    int]],
                                                                    max_input_len:
                                                                    typ-
                                                                    ing.Union[int,
                                                                    NoneType]
                                                                    = None,
                                                                    dropout_keep_prob:
                                                                    float = 1.0,
                                                                    save_checkpoint:
                                                                    typ-
                                                                    ing.Union[str,
                                                                    NoneType]
                                                                    = None,
                                                                    load_checkpoint:
                                                                    typ-
                                                                    ing.Union[str,
                                                                    NoneType]
                                                                    = None) →
                                                                    None

```

Bases: `neuralmonkey.model.model_part.ModelPart`, `neuralmonkey.model.stateful.Stateful`

Encoder processing a sequence using a CNN.

embedded_inputs

```

feed_dict (dataset: neuralmonkey.dataset.Dataset, train: bool = False) → typ-
ing.Dict[tensorflow.python.framework.ops.Tensor, typing.Any]
Populate the feed dictionary with the encoder inputs.

```

Encoder input placeholders:

encoder_input: Stores indices to the vocabulary, shape (batch, time)

encoder_padding: Stores the padding (ones and zeros, indicating valid words and positions after the end of sentence, shape (batch, time)

train_mode: Boolean scalar specifying the mode (train vs runtime)

Parameters

- **dataset** – The dataset to use
- **train** – Boolean flag telling whether it is training time

input_mask

inputs

output

`train_mode`

Module contents

neuralmonkey.evaluators package

Submodules

neuralmonkey.evaluators.accuracy module

class neuralmonkey.evaluators.accuracy.**AccuracyEvaluator** (*name: str = 'Accuracy'*) → None

Bases: object

static compare_scores (*score1: float, score2: float*) → int

class neuralmonkey.evaluators.accuracy.**AccuracySeqLevelEvaluator** (*name: str = 'AccuracySeqLevel'*) → None

Bases: object

static compare_scores (*score1: float, score2: float*) → int

neuralmonkey.evaluators.average module

class neuralmonkey.evaluators.average.**AverageEvaluator** (*name: str*) → None

Bases: object

Just average the numeric output of a runner.

neuralmonkey.evaluators.beer module

class neuralmonkey.evaluators.beer.**BeerWrapper** (*wrapper: str, name: str = 'BEER', encoding: str = 'utf-8'*) → None

Bases: object

Wrapper for BEER scorer.

Paper: <http://aclweb.org/anthology/D14-1025> Code: <https://github.com/stanojevic/beer>

serialize_to_bytes (*sentences: typing.List[typing.List[str]]*) → bytes

neuralmonkey.evaluators.bleu module

class neuralmonkey.evaluators.bleu.**BLEUEvaluator** (*n: int = 4, deduplicate: bool = False, name: typing.Union[str, NoneType] = None*) → None

Bases: object

static bleu (*hypotheses: typing.List[typing.List[str]], references: typing.List[typing.List[typing.List[str]]], ngrams: int = 4, case_sensitive: bool = True*)
Compute BLEU on a corpus with multiple references.

The n-grams are uniformly weighted.

Default is to use smoothing as in reference implementation on: https://github.com/ufal/qtlearn/blob/master/cuni_train/bin/mteval-v13a.pl#L831-L873

Parameters

- **hypotheses** – List of hypotheses
- **references** – List of references. There can be more than one reference.
- **ngrams** – Maximum order of n-grams. Default 4.
- **case_sensitive** – Perform case-sensitive computation. Default True.

static compare_scores (*score1: float, score2: float*) → int

static deduplicate_sentences (*sentences: typing.List[typing.List[str]]*) → typing.List[typing.List[str]]

static effective_reference_length (*hypotheses: typing.List[typing.List[str]], references_list: typing.List[typing.List[typing.List[str]]]*) → int

Compute the effective reference corpus length.

The effective reference corpus length is based on best match length.

Parameters

- **hypotheses** – List of output sentences as lists of words
- **references_list** – List of lists of references (as lists of words)

static merge_max_counters (*counters: typing.List[collections.Counter]*) → collections.Counter
Merge counters using maximum values.

static minimum_reference_length (*hypotheses: typing.List[typing.List[str]], references_list: typing.List[typing.List[str]]*) → int

Compute the minimum reference corpus length.

The minimum reference corpus length is based on the shortest reference sentence length.

Parameters

- **hypotheses** – List of output sentences as lists of words
- **references_list** – List of lists of references (as lists of words)

static modified_ngram_precision (*hypotheses: typing.List[typing.List[str]], references_list: typing.List[typing.List[typing.List[str]]], n: int, case_sensitive: bool*) → typing.Tuple[float, int]

Compute the modified n-gram precision on a list of sentences.

Parameters

- **hypotheses** – List of output sentences as lists of words
- **references_list** – List of lists of reference sentences (as lists of words)
- **n** – n-gram order
- **case_sensitive** – Whether to perform case-sensitive computation

static ngram_counts (*sentence: typing.List[str], n: int, lowercase: bool, delimiter: str = ' '*) → collections.Counter

Get n-grams from a sentence.

Parameters

- **sentence** – Sentence as a list of words
- **n** – n-gram order

- **lowercase** – Convert ngrams to lowercase
- **delimiter** – delimiter to use to create counter entries

neuralmonkey.evaluators.bleu_ref module

```
class neuralmonkey.evaluators.bleu_ref.BLEUReferenceImplWrapper (wrapper,
                                                                name='BLEU',
                                                                encoding='utf-8')
```

Bases: object

Wrapper for TectoMT's wrapper for reference NIST and BLEU scorer.

serialize_to_bytes (sentences: typing.List[typing.List[str]]) → bytes

neuralmonkey.evaluators.chrf module

```
class neuralmonkey.evaluators.chrf.ChrFEvaluator (n: int = 6, beta: float = 1,
                                                  ignored_symbols: typing.Union[typing.List[str], NoneType] = None,
                                                  name: typing.Union[str, NoneType] = None) → None
```

Bases: object

Compute ChrF score.

See <http://www.statmt.org/wmt15/pdf/WMT49.pdf>

neuralmonkey.evaluators.edit_distance module

```
class neuralmonkey.evaluators.edit_distance.EditDistanceEvaluator (name: str = 'Edit distance') → None
```

Bases: object

static compare_scores (score1: float, score2: float) → int

static ratio (str1: str, str2: str) → float

neuralmonkey.evaluators.f1_bio module

```
class neuralmonkey.evaluators.f1_bio.F1Evaluator (name: str = 'F1 measure') → None
```

Bases: object

F1 evaluator for BIO tagging, e.g. NP chunking.

The entities are annotated as beginning of the entity (B), continuation of the entity (I), the rest is outside the entity (O).

static chunk2set (seq: typing.List[str]) → typing.Set[str]

static f1_score (decoded: typing.List[str], reference: typing.List[str]) → float

neuralmonkey.evaluators.gleu module

```
class neuralmonkey.evaluators.gleu.GLEUEvaluator (n: int = 4, deduplicate: bool = False,
                                                name: typing.Union[str, NoneType] =
                                                None) → None
```

Bases: object

Sentence-level evaluation metric correlating with BLEU on corpus-level.

From “Google’s Neural Machine Translation System: Bridging the Gap between Human and Machine Translation” by Wu et al. (<https://arxiv.org/pdf/1609.08144v2.pdf>)

GLEU is the minimum of recall and precision of all n-grams up to n in references and hypotheses.

Ngram counts are based on the bleu methods.

```
static gleu (hypotheses: typing.List[typing.List[str]], references: typing.
             List[typing.List[typing.List[str]]], ngrams: int = 4, case_sensitive: bool = True)
             → float
Compute GLEU on a corpus with multiple references (no smoothing).
```

Parameters

- **hypotheses** – List of hypotheses
- **references** – List of references. There can be more than one reference.
- **ngrams** – Maximum order of n-grams. Default 4.
- **case_sensitive** – Perform case-sensitive computation. Default True.

```
static total_precision_recall (hypotheses: typing.List[typing.List[str]], references_list:
                              typing.List[typing.List[typing.List[str]]], ngrams: int,
                              case_sensitive: bool) → typing.Tuple[float, float]
Compute a modified n-gram precision and recall on a sentence list.
```

Parameters

- **hypotheses** – List of output sentences as lists of words
- **references_list** – List of lists of reference sentences (as lists of words)
- **ngrams** – n-gram order
- **case_sensitive** – Whether to perform case-sensitive computation

neuralmonkey.evaluators.mse module

```
class neuralmonkey.evaluators.mse.MeanSquaredErrorEvaluator (name: str = 'Mean-
                                                             SquaredError') →
                                                             None
```

Bases: object

```
static compare_scores (score1: float, score2: float) → int
```

neuralmonkey.evaluators.multeval module

```
class neuralmonkey.evaluators.multeval.MultEvalWrapper (wrapper: str, name: str = 'Mul-
                                                         tEval', encoding: str = 'utf-8',
                                                         metric: str = 'bleu', language:
                                                         str = 'en') → None
```

Bases: object

Wrapper for mult-eval's reference BLEU and METEOR scorer.

serialize_to_bytes (*sentences*: *typing.List[typing.List[str]]*) → bytes

neuralmonkey.evaluators.ter module

class `neuralmonkey.evaluators.ter.TEREvaluator` (*name*: *str* = 'TER') → None
Bases: object

Compute TER using the pyter library.

neuralmonkey.evaluators.wer module

class `neuralmonkey.evaluators.wer.WEREvaluator` (*name*: *str* = 'WER') → None
Bases: object

Compute WER (word error rate, used in speech recognition).

Module contents

neuralmonkey.model package

Submodules

neuralmonkey.model.model_part module

Basic functionality of all model parts.

class `neuralmonkey.model.model_part.ModelPart` (*name*: *str*, *save_checkpoint*: *str* = None, *load_checkpoint*: *str* = None) → None

Bases: object

Base class of all model parts.

feed_dict (*dataset*: *neuralmonkey.dataset.Dataset*, *train*: *bool*) → *typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Any]*
Prepare feed dicts for part's placeholders from a dataset.

get_dependencies () → *typing.Set[typing.ModelPart]*
Collect recursively all encoders and decoders.

load (*session*: *tensorflow.python.client.session.Session*) → None
Load model part from a checkpoint file.

name
Name of the model part and its variable scope.

save (*session*: *tensorflow.python.client.session.Session*) → None
Save model part to a checkpoint file.

use_scope ()
Return a context manager.
Return a context manager that (re)opens the model part's variable and name scope.

neuralmonkey.model.sequence module

Module which implements the sequence class and a few of its subclasses.

```
class neuralmonkey.model.sequence.EmbeddedFactorSequence (name: str, vocabularies: typing.List[neuralmonkey.vocabulary.Vocabulary],
                                                         data_ids: typing.List[str], embedding_sizes: typing.List[int],
                                                         max_length: int = None, add_start_symbol: bool = False,
                                                         add_end_symbol: bool = False, save_checkpoint: str = None,
                                                         load_checkpoint: str = None) → None
```

Bases: `neuralmonkey.model.sequence.Sequence`

A `Sequence` that stores one or more embedded inputs (factors).

data

Return the sequence data.

A 3D Tensor of shape (batch, time, dimension), where dimension is the sum of the embedding sizes supplied to the constructor.

dimension

Return the sequence dimension.

The sum of the embedding sizes supplied to the constructor.

embedding_matrices

Return a list of embedding matrices for each factor.

```
feed_dict (dataset: neuralmonkey.dataset.Dataset, train: bool = False) → typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Any]
```

Feed the placeholders with the data.

Parameters

- **dataset** – The dataset.
- **train** – A flag whether the train mode is enabled.

Returns The constructed feed dictionary that contains the factor data and the mask.

input_factors

Return a list of 2D placeholders for each factor.

Each placeholder has shape (batch size, time).

mask

Return a 2D placeholder for the sequence mask.

This is shared across factors and must be the same for each of them.

```
tb_embedding_visualization (logdir: str, prj: <module 'tensorflow.contrib.tensorboard.plugins.projector' from
                             '/home/docs/checkouts/readthedocs.org/user_builds/neural-monkey/envs/0.2.3/lib/python3.5/site-packages/tensorflow/contrib/tensorboard/plugins/projector/__init__.py'>)
```

Link embeddings with vocabulary wordlist.

Used for tensorboard visualization.

Parameters

- **logdir** – directory where model is stored
- **projector** – TensorBoard projector for storing linking info.

```
class neuralmonkey.model.sequence.EmbeddedSequence (name: str, vocabulary: neural-
monkey.vocabulary.Vocabulary,
data_id: str, embedding_size:
int, max_length: int = None,
add_start_symbol: bool = False,
add_end_symbol: bool = False,
save_checkpoint: str = None,
load_checkpoint: str = None) →
None
```

Bases: *neuralmonkey.model.sequence.EmbeddedFactorSequence*

A sequence of embedded inputs (for a single factor).

data_id

Return the input data series identifier.

embedding_matrix

Return the embedding matrix for the sequence.

inputs

Return a 2D placeholder for the sequence inputs.

vocabulary

Return the input vocabulary.

```
class neuralmonkey.model.sequence.Sequence (name: str, max_length: int = None,
save_checkpoint: str = None, load_checkpoint:
str = None) → None
```

Bases: *neuralmonkey.model.model_part.ModelPart*

Base class for a data sequence.

This class represents a batch of sequences of Tensors of possibly different lengths.

data

Return the sequence data.

A *Tensor* representing the data in the sequence. The first and second dimension correspond to batch size and time respectively.

dimension

Return the sequence dimension.

The dimension of the sequence. For 3D sequences, this is the size of the last dimension of the *data* tensor.

lengths

Return the sequence lengths.

A 1D *Tensor* of type *int32* that stores the lengths of the sequences in the batch.

mask

Return the sequence mask.

A 2D *Tensor* of type *float32* and shape (batch size, time) that masks the sequences in the batch.

max_length

Return the maximum length of sequences in the *data* tensor.

neuralmonkey.model.stateful module

Module that provides classes that encapsulate model parts with states.

There are three classes: *Stateful*, *TemporalStateful*, and *SpatialStateful*.

Model parts that do not keep states in time but have a single tensor on the output should be instances of *Stateful*. Model parts that keep their hidden states in a time-oriented list (e.g. recurrent encoder) should be instances of *TemporalStateful*. Model parts that keep the states in a 2D matrix (e.g. image encoders) should be instances of *SpatialStateful*.

There are also classes that inherit from both stateful and temporal or spatial stateful (e.g. *TemporalStatefulWithOutput*) that can be used for model parts that satisfy more requirements (e.g. recurrent encoder).

class `neuralmonkey.model.stateful.SpatialStateful`

Bases: `object`

spatial_mask

Return mask for the `spatial_states`.

A 3D *Tensor* of shape (batch, width, height) of type float32 which masks the spatial states that they can be of different shapes. The mask should only contain ones or zeros.

spatial_states

Return object states in space.

A 4D *Tensor* of shape (batch, width, height, state_size) which contains the states of the object in space (e.g. final layer of a convolution network processing an image).

class `neuralmonkey.model.stateful.SpatialStatefulWithOutput`

Bases: `neuralmonkey.model.stateful.Stateful`, `neuralmonkey.model.stateful.SpatialStateful`

class `neuralmonkey.model.stateful.Stateful`

Bases: `object`

output

Return the object output.

A 2D *Tensor* of shape (batch, state_size) which contains the resulting state of the object.

class `neuralmonkey.model.stateful.TemporalStateful`

Bases: `object`

temporal_mask

Return mask for the `temporal_states`.

A 2D *Tensor* of shape (batch, time) of type float32 which masks the temporal states so each sequence can have a different length. It should only contain ones or zeros.

temporal_states

Return object states in time.

A 3D *Tensor* of shape (batch, time, state_size) which contains the states of the object in time (e.g. hidden states of a recurrent encoder).

class `neuralmonkey.model.stateful.TemporalStatefulWithOutput`

Bases: `neuralmonkey.model.stateful.Stateful`, `neuralmonkey.model.stateful.TemporalStateful`

Module contents

neuralmonkey.nn package

Submodules

neuralmonkey.nn.highway module

Module implementing the highway networks.

```
neuralmonkey.nn.highway.highway(inputs, activation=<function relu>,
                                   scope='HighwayNetwork')
```

Create a single highway layer.

$$y = H(x, W_h) * T(x, W_t) + x * C(x, W_c)$$

where:

$$C(x, W_c) = 1 - T(x, W_t)$$

Parameters

- **inputs** – A tensor or list of tensors. It should be 2D tensors with equal length in the first dimension (batch size)
- **activation** – Activation function of the linear part of the formula $H(x, W_h)$.
- **scope** – The name of the scope used for the variables.

Returns A tensor of shape `tf.shape(inputs)`

neuralmonkey.nn.mlp module

```
class neuralmonkey.nn.mlp.MultilayerPerceptron(mlp_input: tensorflow.python.framework.ops.Tensor,
                                                layer_configuration: typing.List[int],
                                                dropout_keep_prob: float, output_size: int, train_mode: tensorflow.python.framework.ops.Tensor,
                                                activation_fn: typing.Callable[[tensorflow.python.framework.ops.Tensor], tensorflow.python.framework.ops.Tensor]
                                                = <function relu>, name: str = 'multilayer_perceptron') → None
```

Bases: object

General implementation of the multilayer perceptron.

classification

softmax

neuralmonkey.nn.noisy_gru_cell module

```
class neuralmonkey.nn.noisy_gru_cell.NoisyGRUCell(num_units: int, training) → None
```

Bases: tensorflow.python.ops.rnn_cell_impl.RNNCell

Gated Recurrent Unit cell (cf. <http://arxiv.org/abs/1406.1078>).

GRU with noisy activation functions (<http://arxiv.org/abs/1603.00391>). The theano code is available at https://github.com/caglar/noisy_units.

It is based on the TensorFlow implementatin of GRU just the activation function are changed for the noisy ones.

output_size

state_size

`neuralmonkey.nn.noisy_gru_cell.noisy_activation(x, generic, linearized, training, alpha: float = 1.1, c: float = 0.5)`

Apply the noisy activation.

Implements the noisy activation with Half-Normal Noise for Hard-Saturation functions.

See <http://arxiv.org/abs/1603.00391>, Algorithm 1.

Parameters

- **x** – Tensor which is an input to the activation function
- **generic** – The generic formulation of the activation function. (denoted as h in the paper)
- **linearized** – Linearization of the activation based on the first-order Taylor expansion around zero. (denoted as u in the paper)
- **training** – A boolean tensor telling whether we are in the training stage (and the noise is sampled) or in runtime when the expectation is used instead.
- **alpha** – Mixing hyper-parameter. The leakage rate from the linearized function to the nonlinear one.
- **c** – Standard deviation of the sampled noise.

`neuralmonkey.nn.noisy_gru_cell.noisy_sigmoid(x, training)`

`neuralmonkey.nn.noisy_gru_cell.noisy_tanh(x, training)`

neuralmonkey.nn.ortho_gru_cell module

class `neuralmonkey.nn.ortho_gru_cell.NematusGRUCell(rnn_size, use_state_bias=False, use_input_bias=True)`

Bases: `tensorflow.python.ops.rnn_cell_impl.GRUCell`

Nematus implementation of gated recurrent unit cell.

The main difference is the order in which the gating functions and linear projections are applied to the hidden state.

The math is equivalent, in practice there are differences due to float precision errors.

call (`inputs, state`)

Gated recurrent unit (GRU) with nunits cells.

class `neuralmonkey.nn.ortho_gru_cell.OrthoGRUCell(num_units, activation=None, reuse=None, bias_initializer=None)`

Bases: `tensorflow.python.ops.rnn_cell_impl.GRUCell`

Classic GRU cell but initialized using random orthogonal matrices.

neuralmonkey.nn.pervasive_dropout_wrapper module

```
class neuralmonkey.nn.pervasive_dropout_wrapper.PervasiveDropoutWrapper(cell,
                                                                    mask,
                                                                    scale)
    →
    None

Bases: tensorflow.python.ops.rnn_cell_impl.RNNCell

output_size
state_size
```

neuralmonkey.nn.projection module

Module which implements various types of projections.

```
neuralmonkey.nn.projection.glu(input_: tensorflow.python.framework.ops.Tensor, gating_fn: typing.Callable[[tensorflow.python.framework.ops.Tensor], tensorflow.python.framework.ops.Tensor] = <function sigmoid>) → tensorflow.python.framework.ops.Tensor
```

Apply a Gated Linear Unit.

Gated Linear Unit - Dauphin et al. (2016).

<http://arxiv.org/abs/1612.08083>

```
neuralmonkey.nn.projection.maxout(inputs: tensorflow.python.framework.ops.Tensor, size: int, scope: str = 'MaxoutProjection') → tensorflow.python.framework.ops.Tensor
```

Apply a maxout operation.

Implementation of Maxout layer (Goodfellow et al., 2013).

<http://arxiv.org/pdf/1302.4389.pdf>

$z = Wx + b$ $y_i = \max(z_{2i-1}, z_{2i})$

Parameters

- **inputs** – A tensor or list of tensors. It should be 2D tensors with equal length in the first dimension (batch size)
- **size** – The size of dimension 1 of the output tensor.
- **scope** – The name of the scope used for the variables

Returns A tensor of shape batch x size

```
neuralmonkey.nn.projection.multilayer_projection (input_: tensorflow.python.framework.ops.Tensor,
layer_sizes: typing.List[int],
train_mode: tensorflow.python.framework.ops.Tensor,
activation: typing.Callable[[tensorflow.python.framework.ops.Tensor],
tensorflow.python.framework.ops.Tensor] =
<function relu>, dropout_keep_prob:
float = 1.0, scope: str
= 'mlp') → tensorflow.python.framework.ops.Tensor
```

neuralmonkey.nn.utils module

Module which provides utility functions used across the package.

```
neuralmonkey.nn.utils.dropout (variable: tensorflow.python.framework.ops.Tensor, keep_prob:
float, train_mode: tensorflow.python.framework.ops.Tensor) →
tensorflow.python.framework.ops.Tensor
```

Perform dropout on a variable, depending on mode.

Parameters

- **variable** – The variable to be dropped out
- **keep_prob** – The probability of keeping a value in the variable
- **train_mode** – A bool Tensor specifying whether to dropout or not

Module contents

neuralmonkey.processors package

Submodules

neuralmonkey.processors.alignment module

```
class neuralmonkey.processors.alignment.WordAlignmentPreprocessor (source_len,
target_len,
dtype=<class
'numpy.float32'>,
normal-
ize=True,
zero_based=True)
```

Bases: object

A preprocessor for word alignments in a text format.

One of the following formats is expected:

```
s1-t1 s2-t2 ...
```

```
s1:1/w1 s2:t2/w2 ...
```

where each s and t is the index of a word in the source and target sentence, respectively, and w is the corresponding weight. If the weight is not given, it is assumed to be 1. The separators - and : are interchangeable.

The output of the preprocessor is an alignment matrix of the fixed shape (target_len, source_len) for each sentence.

neuralmonkey.processors.bpe module

class neuralmonkey.processors.bpe.**BPEPostprocessor** (*separator: str = '@@'*) → None
Bases: object

decode (*sentence: typing.List[str]*) → typing.List[str]

class neuralmonkey.processors.bpe.**BPEPreprocessor** (*merge_file: str, separator: str = '@@', encoding: str = 'utf-8'*) → None

Bases: object

Wrapper class for Byte-Pair Encoding.

Paper: <https://arxiv.org/abs/1508.07909> Code: <https://github.com/rsennrich/subword-nmt>

neuralmonkey.processors.editops module

class neuralmonkey.processors.editops.**Postprocess** (*source_id: str, edits_id: str, result_postprocess: typing.Callable[[typing.Iterable[typing.List[str]]], typing.Iterable[typing.List[str]]] = None*) → None

Bases: object

Preprocessor applying edit operations on a series.

class neuralmonkey.processors.editops.**Preprocess** (*source_id: str, target_id: str*) → None
Bases: object

Preprocessor transforming two series into series of edit operations.

neuralmonkey.processors.editops.**convert_to_edits** (*source: typing.List[str], target: typing.List[str]*) → typing.List[str]

neuralmonkey.processors.editops.**reconstruct** (*source: typing.List[str], edits: typing.List[str]*) → typing.List[str]

neuralmonkey.processors.german module

class neuralmonkey.processors.german.**GermanPostprocessor** (*compounding=True, contracting=True, pronouns=True*)

Bases: object

decode (*sentence*)

class neuralmonkey.processors.german.**GermanPreprocessor** (*compounding=True, contracting=True, pronouns=True*)

Bases: object

neuralmonkey.processors.helpers module

`neuralmonkey.processors.helpers.pipeline` (*processors: typing.List[typing.Callable]*) → `typing.Callable`

Concatenate processors.

`neuralmonkey.processors.helpers.postprocess_char_based` (*sentences: typing.List[typing.List[str]]*) → `typing.List[typing.List[str]]`

`neuralmonkey.processors.helpers.preprocess_char_based` (*sentence: typing.List[str]*) → `typing.List[str]`

`neuralmonkey.processors.helpers.untruecase` (*sentences: typing.List[typing.List[str]]*) → `typing.Generator[[typing.List[str], NoneType], NoneType]`

neuralmonkey.processors.speech module

`neuralmonkey.processors.speech.SpeechFeaturesPreprocessor` (*feature_type: str = 'mfcc', delta_order: int = 0, delta_window: int = 2, **kwargs*) → `typing.Callable`

Calculate speech features.

First, the given type of features (e.g. MFCC) is computed using a window of length *winlen* and step *winstep*; for additional keyword arguments (specific to each feature type), see <http://python-speech-features.readthedocs.io/>. Then, delta features up to *delta_order* are added.

By default, 13 MFCCs per frame are computed. To add delta and delta-delta features (resulting in 39 coefficients per frame), set *delta_order=2*.

Parameters

- **feature_type** – mfcc, fbank, logfbank or ssc (default is mfcc)
- **delta_order** – maximum order of the delta features (default is 0)
- **delta_window** – window size for delta features (default is 2)
- ****kwargs** – keyword arguments for the appropriate function from `python_speech_features`

Returns A numpy array of shape `[num_frames, num_features]`.

Module contents

neuralmonkey.readers package

Submodules

neuralmonkey.readers.audio_reader module

`class neuralmonkey.readers.audio_reader.Audio` (*rate, data*)
Bases: `tuple`

data

Alias for field number 1

rate

Alias for field number 0

`neuralmonkey.readers.audio_reader.audio_reader` (*prefix: str = ''*, *audio_format: str = 'wav'*) → `typing.Callable`

Get a reader of audio files loading them from a list of paths.

Parameters **prefix** – Prefix of the paths to the audio files.

Returns The reader function that takes a list of audio file paths (relative to provided prefix) and returns a list of numpy arrays.

neuralmonkey.readers.image_reader module

`neuralmonkey.readers.image_reader.image_reader` (*prefix=''*, *pad_w: typing.Union[int, NoneType] = None*, *pad_h: typing.Union[int, NoneType] = None*, *rescale_w: bool = False*, *rescale_h: bool = False*, *keep_aspect_ratio: bool = False*, *mode: str = 'RGB'*) → `typing.Callable`

Get a reader of images loading them from a list of paths.

Parameters

- **prefix** – Prefix of the paths that are listed in a image files.
- **pad_w** – Width to which the images will be padded/cropped/resized.
- **pad_h** – Height to with the images will be padded/corpped/resized.
- **rescale_w** – If true, image is rescaled to have given width. It is cropped/padded otherwise.
- **rescale_h** – If true, image is rescaled to have given height. It is cropped/padded otherwise.
- **keep_aspect_ratio** – Flag whether the aspect ration should be kept during rescaling. Can only be used if both width and height are rescaled.
- **mode** – Scipy image loading mode, see scipy documentation for more details.

Returns The reader function that takes a list of image paths (relative to provided prefix) and returns a list of images as numpy arrays of shape pad_h x pad_w x number of channels.

`neuralmonkey.readers.image_reader.imagenet_reader` (*prefix: str*, *target_width: int = 227*, *target_height: int = 227*) → `typing.Callable`

Load and prepare image the same way as Caffe scripts.

neuralmonkey.readers.numpy_reader module

`neuralmonkey.readers.numpy_reader.numpy_reader` (*files: typing.List[str]*)

neuralmonkey.readers.plain_text_reader module

```
neuralmonkey.readers.plain_text_reader.UtfPlainTextReader (files:          typ-
                                                                ing.List[str]) → typ-
                                                                ing.Iterable[typing.List[str]]
```

```
neuralmonkey.readers.plain_text_reader.column_separated_reader (column:      int,
                                                                delimiter: str =
                                                                '\t', quotechar:
                                                                str = None,
                                                                encoding: str =
                                                                'utf-8') → typ-
                                                                ing.Callable[[typing.List[str]],
                                                                typ-
                                                                ing.Iterable[typing.List[str]]]
```

Get reader for delimiter-separated tokenized text.

Parameters **column** – number of column to be returned. It starts with 1 for the first

```
neuralmonkey.readers.plain_text_reader.csv_reader (column: int)
```

```
neuralmonkey.readers.plain_text_reader.string_reader (encoding: str = 'utf-8') → typ-
                                                                ing.Callable[[typing.List[str]],
                                                                typing.Iterable[str]]
```

```
neuralmonkey.readers.plain_text_reader.tokenized_text_reader (encoding: str =
                                                                'utf-8') → typ-
                                                                ing.Callable[[typing.List[str]],
                                                                typ-
                                                                ing.Iterable[typing.List[str]]]
```

Get reader for space-separated tokenized text.

```
neuralmonkey.readers.plain_text_reader.tsv_reader (column: int)
```

neuralmonkey.readers.string_vector_reader module

```
neuralmonkey.readers.string_vector_reader.FloatVectorReader (files:          typ-
                                                                ing.List[str]) → typ-
                                                                ing.Iterable[typing.List[numpy.ndarray]]
```

```
neuralmonkey.readers.string_vector_reader.IntVectorReader (files:          typ-
                                                                ing.List[str]) → typ-
                                                                ing.Iterable[typing.List[numpy.ndarray]]
```

```
neuralmonkey.readers.string_vector_reader.get_string_vector_reader (dtype:
                                                                typing.Type
                                                                = <class
                                                                'numpy.float32'>,
                                                                columns:
                                                                int      =
                                                                None)
```

Get a reader for vectors encoded as whitespace-separated numbers.

Module contents

neuralmonkey.runners package

Submodules

neuralmonkey.runners.base_runner module

class neuralmonkey.runners.base_runner.**BaseRunner** (*output_series: str, decoder: neuralmonkey.model.model_part.ModelPart*)
 → None

Bases: object

decoder_data_id

get_executable (*compute_losses: bool = False, summaries: bool = True*) → neuralmonkey.runners.base_runner.Executable

loss_names

class neuralmonkey.runners.base_runner.**Executable**

Bases: object

collect_results (*results: typing.List[typing.Dict]*) → None

next_to_execute () → typing.Tuple[typing.Set[neuralmonkey.model.model_part.ModelPart], typing.Union[typing.Dict, typing.List], typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Union[int, float, numpy.ndarray]]]

class neuralmonkey.runners.base_runner.**ExecutionResult** (*outputs, losses, scalar_summaries, histogram_summaries, image_summaries*)

Bases: tuple

histogram_summaries
 Alias for field number 3

image_summaries
 Alias for field number 4

losses
 Alias for field number 1

outputs
 Alias for field number 0

scalar_summaries
 Alias for field number 2

neuralmonkey.runners.base_runner.**reduce_execution_results** (*execution_results: typing.List[neuralmonkey.runners.base_runner.ExecutionResult]*)
 → neuralmonkey.runners.base_runner.ExecutionResult

Aggregate execution results into one.

neuralmonkey.runners.beamsearch_runner module

```

class neuralmonkey.runners.beamsearch_runner.BeamSearchExecutable (rank: int,
all_encoders:
    typing.Set[neuralmonkey.model.model_part.ModelPart],
bs_outputs:
    neuralmonkey.decoders.beam_search_decoder.BeamSearchDecoder,
vocabulary:
    neuralmonkey.vocabulary.Vocabulary,
postprocess: typing.Union[typing.Callable,
NoneType]) → None

```

Bases: *neuralmonkey.runners.base_runner.Executable*

collect_results (*results: typing.List[typing.Dict]*) → None

next_to_execute () → typing.Tuple[typing.Set[neuralmonkey.model.model_part.ModelPart], typing.Union[typing.Dict, typing.List], typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Union[int, float, numpy.ndarray]]]

```

class neuralmonkey.runners.beamsearch_runner.BeamSearchRunner (output_series:
    str, decoder: neuralmonkey.decoders.beam_search_decoder.BeamSearchDecoder,
rank: int = 1,
postprocess: typing.Callable[[typing.List[str]],
typing.List[str]] =
None) → None

```

Bases: *neuralmonkey.runners.base_runner.BaseRunner*

decoder_data_id

get_executable (*compute_losses: bool = False, summaries: bool = True*) → neuralmonkey.runners.beamsearch_runner.BeamSearchExecutable

loss_names

```

neuralmonkey.runners.beamsearch_runner.beam_search_runner_range (output_series:
    str, decoder:
    neuralmonkey.decoders.beam_search_decoder.BeamSearchDecoder,
max_rank: int
= None, postprocess: typing.Callable[[typing.List[str]],
typing.List[str]]
= None)
→ typing.List[neuralmonkey.runners.beamsearch_runner.BeamSearchRunner]

```

Return beam search runners for a range of ranks from 1 to max_rank.

This means there is max_rank output series where the n-th series contains the n-th best hypothesis from the beam search.

Parameters

- **output_series** – Prefix of output series.
- **decoder** – Beam search decoder shared by all runners.
- **max_rank** – Maximum rank of the hypotheses.
- **postprocess** – Series-level postprocess applied on output.

Returns List of beam search runners getting hypotheses with rank from 1 to max_rank.

neuralmonkey.runners.label_runner module

```
class neuralmonkey.runners.label_runner.LabelRunExecutable (all_coders, fetches, vo-
                                                            cabulary, postprocess)
    Bases: neuralmonkey.runners.base_runner.Executable
    collect_results (results: typing.List[typing.Dict]) → None
    next_to_execute () → typing.Tuple[typing.Set[neuralmonkey.model.model_part.ModelPart], typ-
                                     ing.Union[typing.Dict, typing.List], typing.Dict[tensorflow.python.framework.ops.Tensor,
                                     typing.Union[int, float, numpy.ndarray]]]
    Get the feedables and tensors to run.

class neuralmonkey.runners.label_runner.LabelRunner (output_series: str; decoder:
                                                       typing.Any; postprocess: typ-
                                                       ing.Callable[[typing.List[str]],
                                                       typing.List[str]] = None) → None
    Bases: neuralmonkey.runners.base_runner.BaseRunner
    get_executable (compute_losses=False, summaries=True)
    loss_names
```

neuralmonkey.runners.logits_runner module

A runner outputting logits or normalized distribution from a decoder.

```
class neuralmonkey.runners.logits_runner.LogitsExecutable (all_coders: typing.
                                                           Set[neuralmonkey.model.model_part.ModelPart],
                                                           fetches: typing.
                                                           Dict[tensorflow.python.framework.ops.Tensor,
                                                           typing.Union[int, float,
                                                           numpy.ndarray]], vo-
                                                           cabulary: neural-
                                                           monkey.vocabulary.Vocabulary,
                                                           normalize: bool = True,
                                                           pick_index: int = None)
    → None
    Bases: neuralmonkey.runners.base_runner.Executable
    collect_results (results: typing.List[typing.Dict]) → None
    next_to_execute () → typing.Tuple[typing.Set[neuralmonkey.model.model_part.ModelPart], typ-
                                     ing.Union[typing.Dict, typing.List], typing.Dict[tensorflow.python.framework.ops.Tensor,
                                     typing.Union[int, float, numpy.ndarray]]]
    Get the feedables and tensors to run.
```

```
class neuralmonkey.runners.logits_runner.LogitsRunner (output_series: str, decoder: typing.Any, normalize: bool = True, pick_index: int = None, pick_value: str = None) → None
```

Bases: *neuralmonkey.runners.base_runner.BaseRunner*

A runner which takes the output from decoder.decoded_logits.

The logits / normalized probabilities are outputted as tab-separated string values. If the decoder produces a list of logits (as the recurrent decoder), the tab separated arrays are separated with commas. Alternatively, we may be interested in a single distribution dimension.

```
get_executable (compute_losses: bool = False, summaries: bool = True) → neuralmonkey.runners.logits_runner.LogitsExecutable
```

loss_names

neuralmonkey.runners.perplexity_runner module

```
class neuralmonkey.runners.perplexity_runner.PerplexityExecutable (all_coders: typing.Set[neuralmonkey.model.model_part.ModelPart], xent_op: tensorflow.python.framework.ops.Tensor) → None
```

Bases: *neuralmonkey.runners.base_runner.Executable*

```
collect_results (results: typing.List[typing.Dict]) → None
```

```
next_to_execute () → typing.Tuple[typing.Set[neuralmonkey.model.model_part.ModelPart], typing.Union[typing.Dict, typing.List], typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Union[int, float, numpy.ndarray]]]
    Get the feedables and tensors to run.
```

```
class neuralmonkey.runners.perplexity_runner.PerplexityRunner (output_series: str, decoder: neuralmonkey.decoders.decoder.Decoder) → None
```

Bases: *neuralmonkey.runners.base_runner.BaseRunner*

```
get_executable (compute_losses=False, summaries=True) → neuralmonkey.runners.perplexity_runner.PerplexityExecutable
```

loss_names

neuralmonkey.runners.plain_runner module

```
class neuralmonkey.runners.plain_runner.PlainExecutable (all_coders, fetches, vocabulary, postprocess) → None
```

Bases: *neuralmonkey.runners.base_runner.Executable*

```
collect_results (results: typing.List[typing.Dict]) → None
```

```
next_to_execute () → typing.Tuple[typing.Set[neuralmonkey.model.model_part.ModelPart], typing.Union[typing.Dict, typing.List], typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Union[int, float, numpy.ndarray]]]
    Get the feedables and tensors to run.
```

```
class neuralmonkey.runners.plain_runner.PlainRunner (output_series: str, decoder:
                                                    typing.Any, postprocess: typ-
                                                    ing.Callable[[typing.List[str]],
                                                    typing.List[str]] = None) → None
```

Bases: *neuralmonkey.runners.base_runner.BaseRunner*

A runner which takes the output from decoder.decoded.

```
get_executable (compute_losses=False, summaries=True)
```

```
loss_names
```

neuralmonkey.runners.regression_runner module

```
class neuralmonkey.runners.regression_runner.RegressionRunExecutable (all_coders:
                                                                    typ-
                                                                    ing.Set[neuralmonkey.model.model.
                                                                    fetches:
                                                                    typ-
                                                                    ing.Dict[str,
                                                                    tensor-
                                                                    flow.python.framework.ops.Tensor],
                                                                    postpro-
                                                                    cess: typ-
                                                                    ing.Callable[[float],
                                                                    float] =
                                                                    None) →
                                                                    None
```

Bases: *neuralmonkey.runners.base_runner.Executable*

```
collect_results (results: typing.List[typing.Dict]) → None
```

```
next_to_execute () → typing.Tuple[typing.Set[neuralmonkey.model.model_part.ModelPart], typ-
                                     ing.Union[typing.Dict, typing.List], typing.Dict[tensorflow.python.framework.ops.Tensor,
                                     typing.Union[int, float, numpy.ndarray]]]
```

Get the feedables and tensors to run.

```
class neuralmonkey.runners.regression_runner.RegressionRunner (output_series:
                                                                str, decoder: neural-
                                                                monkey.decoders.sequence_regressor.Sequenc
                                                                postprocess: typ-
                                                                ing.Callable[[float],
                                                                float] = None) →
                                                                None
```

Bases: *neuralmonkey.runners.base_runner.BaseRunner*

```
get_executable (compute_losses: bool = False, summaries: bool = True) → neural-
                                                         monkey.runners.base_runner.Executable
```

```
loss_names
```

neuralmonkey.runners.representation_runner module

A runner that prints out the input representation from an encoder.

```

class neuralmonkey.runners.representation_runner.RepresentationExecutable (prev_coders:
                                                                    typ-
                                                                    ing.Set[neuralmonkey.model
                                                                    en-
                                                                    coded:
                                                                    ten-
                                                                    sor-
                                                                    flow.python.framework.ops.
                                                                    used_session:
                                                                    int)
                                                                    →
                                                                    None

```

Bases: *neuralmonkey.runners.base_runner.Executable*

collect_results (*results: typing.List[typing.Dict]*) → None

next_to_execute () → typing.Tuple[typing.Set[neuralmonkey.model.model_part.ModelPart], typing.Union[typing.Dict, typing.List], typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Union[int, float, numpy.ndarray]]]

```

class neuralmonkey.runners.representation_runner.RepresentationRunner (output_series:
                                                                    str, en-
                                                                    coder:
                                                                    neural-
                                                                    monkey.model.stateful.Stateful,
                                                                    used_session:
                                                                    int = 0)
                                                                    → None

```

Bases: *neuralmonkey.runners.base_runner.BaseRunner*

Runner printing out representation from a encoder.

Using this runner is the way how to get input / other data representation out from Neural Monkey.

get_executable (*compute_losses: bool = False, summaries: bool = True*) → neuralmonkey.runners.representation_runner.RepresentationExecutable

loss_names

neuralmonkey.runners.runner module

```

class neuralmonkey.runners.runner.GreedyRunExecutable (all_coders, fetches, vocabulary,
                                                                    postprocess) → None

```

Bases: *neuralmonkey.runners.base_runner.Executable*

collect_results (*results: typing.List[typing.Dict]*) → None

next_to_execute () → typing.Tuple[typing.Set[neuralmonkey.model.model_part.ModelPart], typing.Union[typing.Dict, typing.List], typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Union[int, float, numpy.ndarray]]]

Get the feedables and tensors to run.

```

class neuralmonkey.runners.runner.GreedyRunner (output_series:          str,          decoder:
                                                                    typing.Any,          postprocess:          typ-
                                                                    ing.Callable[[typing.List[str]],          typ-
                                                                    ing.List[str]] = None) → None

```

Bases: *neuralmonkey.runners.base_runner.BaseRunner*

get_executable (*compute_losses=False, summaries=True*)

loss_names

neuralmonkey.runners.word_alignment_runner module

```
class neuralmonkey.runners.word_alignment_runner.WordAlignmentRunner (output_series:
                                                                    str, en-
                                                                    coder:
                                                                    neural-
                                                                    monkey.model.model_part.ModelPart
                                                                    decoder:
                                                                    neural-
                                                                    monkey.decoders.decoder.Decoder)
                                                                    → None
```

Bases: *neuralmonkey.runners.base_runner.BaseRunner*

get_executable (*compute_losses=False, summaries=True*)

loss_names

```
class neuralmonkey.runners.word_alignment_runner.WordAlignmentRunnerExecutable (all_coders,
                                                                    fetches)
```

Bases: *neuralmonkey.runners.base_runner.Executable*

collect_results (*results: typing.List[typing.Dict]*) → None

next_to_execute () → *typing.Tuple[typing.Set[neuralmonkey.model.model_part.ModelPart], typing.Union[typing.Dict, typing.List], typing.Dict[tensorflow.python.framework.ops.Tensor, typing.Union[int, float, numpy.ndarray]]]*

Get the feedables and tensors to run.

Module contents

neuralmonkey.tests package

Submodules

neuralmonkey.tests.test_bleu module

```
class neuralmonkey.tests.test_bleu.TestBLEU (methodName='runTest')
```

Bases: *unittest.case.TestCase*

test_bleu ()

test_empty_decoded ()

test_empty_reference ()

test_empty_sentence ()

test_identical ()

neuralmonkey.tests.test_config module

Tests the config parsing module.

```
class neuralmonkey.tests.test_config.TestParsing (methodName='runTest')
```

Bases: *unittest.case.TestCase*

test_splitter_bad_brackets ()

```
neuralmonkey.tests.test_config.test_splitter_gen(a, b)
```

neuralmonkey.tests.test_dataset module

```
class neuralmonkey.tests.test_dataset.TestDataset (methodName='runTest')
    Bases: unittest.case.TestCase
        test_nonexistent_file()
```

neuralmonkey.tests.test_decoder module

Unit tests for the decoder. (Tests only initialization so far)

```
class neuralmonkey.tests.test_decoder.TestDecoder (methodName='runTest')
    Bases: unittest.case.TestCase
        test_init()
```

neuralmonkey.tests.test_encoders_init module

Test init methods of encoders.

```
class neuralmonkey.tests.test_encoders_init.TestEncodersInit (methodName='runTest')
    Bases: unittest.case.TestCase
        test_post_cnn_encoder()
        test_sentence_cnn_encoder()
        test_sentence_encoder()
        test_vector_encoder()
```

```
neuralmonkey.tests.test_encoders_init.traverse_combinations (params:          typing.Dict[str, typing.List[typing.Any]],
                                                                    partial_params:
                                                                    typing.Dict[str,
                                                                    typing.Any]) → typing.Iterable[typing.Dict[str,
                                                                    typing.Any]]
```

neuralmonkey.tests.test_eval_wrappers module

```
class neuralmonkey.tests.test_eval_wrappers.TestAccuracyEvaluator (methodName='runTest')
    Bases: unittest.case.TestCase
        setUp()
        test_seq_level_acc()
        test_word_level_acc()

class neuralmonkey.tests.test_eval_wrappers.TestExternalEvaluators (methodName='runTest')
    Bases: unittest.case.TestCase
        test_beer()
```

```
test_f1()
test_gleu()
test_multeval_bleu()
test_multeval_meteor()
test_multeval_ter()
```

neuralmonkey.tests.test_functions module

Unit tests for functions.py.

```
class neuralmonkey.tests.test_functions.TestPiecewiseFunction (methodName='runTest')
    Bases: unittest.case.TestCase
    test_piecewise_constant()
```

neuralmonkey.tests.test_model_part module

Test ModelPart class.

```
class neuralmonkey.tests.test_model_part.Test (methodName='runTest')
    Bases: unittest.case.TestCase
    Test capabilities of model part.
    test_save_and_load()
        Try to save and load encoder.
```

neuralmonkey.tests.test_nn_utils module

```
class neuralmonkey.tests.test_nn_utils.TestDropout (methodName='runTest')
    Bases: unittest.case.TestCase
    test_invalid_keep_prob()
        Tests invalid dropout values
    test_keep_prob()
        Counts dropped items and compare with the expectation
    test_train_false()
        Checks that dropout is not used when not training
```

neuralmonkey.tests.test_readers module

Unit tests for readers

```
class neuralmonkey.tests.test_readers.TestStringVectorReader (methodName='runTest')
    Bases: unittest.case.TestCase
    setUp()
    tearDown()
    test_columns()
    test_reader()
```

neuralmonkey.tests.test_ter module

```
class neuralmonkey.tests.test_ter.TestBLEU (methodName='runTest')  
    Bases: unittest.case.TestCase  
  
    test_empty_decoded()  
    test_empty_reference()  
    test_empty_sentence()  
    test_identical()  
    test_ter()
```

neuralmonkey.tests.test_vocabulary module

```
class neuralmonkey.tests.test_vocabulary.TestVocabulary (methodName='runTest')  
    Bases: unittest.case.TestCase  
  
    test_all_words_in()  
    test_count_fail()  
    test_min_freq()  
    test_padding()  
    test_there_and_back_self()  
    test_unknown_word()  
    test_weights()
```

Module contents

neuralmonkey.trainers package

Submodules

neuralmonkey.trainers.cross_entropy_trainer module

```
class neuralmonkey.trainers.cross_entropy_trainer.CrossEntropyTrainer (decoders:
    typing.List[typing.Any],
    decoder_weights:
    typing.List[typing.Union[tensorflow.python.nn.initializers.Initializer,
    float,
    NoneType]]
    = None,
    l1_weight=0.0,
    l2_weight=0.0,
    clip_norm=False,
    optimizer=None,
    global_step=None,
    var_scopes:
    typing.List[str]
    = None,
    var_collection:
    str =
    None)
    → None
```

Bases: *neuralmonkey.trainers.generic_trainer.GenericTrainer*

```
neuralmonkey.trainers.cross_entropy_trainer.xent_objective (decoder,
    weight=None)
    → neuralmonkey.trainers.generic_trainer.Objective
```

Get XENT objective from decoder with cost.

neuralmonkey.trainers.generic_trainer module

```
class neuralmonkey.trainers.generic_trainer.GenericTrainer (objectives:          typ-
ing.List[neuralmonkey.trainers.generic_trainer.Obj
l1_weight: float = 0.0,
l2_weight: float = 0.0,
clip_norm: float =
None, optimizer=None,
global_step=None,
var_scopes:          typ-
ing.List[str] = None,
var_collection: str =
None) → None
```

Bases: object

```
get_executable (compute_losses=True,          summaries=True)          →          neural-
monkey.runners.base_runner.Executable
```

```
class neuralmonkey.trainers.generic_trainer.Objective (name, decoder, loss, gradients,
weight)
```

Bases: tuple

decoder

Alias for field number 1

gradients

Alias for field number 3

loss

Alias for field number 2

name

Alias for field number 0

weight

Alias for field number 4

```
class neuralmonkey.trainers.generic_trainer.TrainExecutable (all_coders,
train_op,          losses,
scalar_summaries,
histogram_summaries)
```

Bases: *neuralmonkey.runners.base_runner.Executable*

```
collect_results (results: typing.List[typing.Dict]) → None
```

```
next_to_execute () → typing.Tuple[typing.Set[neuralmonkey.model.model_part.ModelPart], typ-
ing.Union[typing.Dict, typing.List], typing.Dict[tensorflow.python.framework.ops.Tensor,
typing.Union[int, float, numpy.ndarray]]]
```

neuralmonkey.trainers.self_critical_objective module

Training objective for self-critical learning.

Self-critic learning is a modification of the REINFORCE algorithm that uses the reward of the train-time decoder output as a baseline in the update step.

For more details see: <https://arxiv.org/pdf/1612.00563.pdf>

`neuralmonkey.trainers.self_critical_objective.reinforce_score` (*reward: tensor-flow.python.framework.ops.Tensor, baseline: tensor-flow.python.framework.ops.Tensor, decoded: tensor-flow.python.framework.ops.Tensor, logits: tensor-flow.python.framework.ops.Tensor*)
 → *tensor-flow.python.framework.ops.Tensor*

Cost function whose derivative is the REINFORCE equation.

This implements the primitive function to the central equation of the REINFORCE algorithm that estimates the gradients of the loss with respect to decoder logits.

It uses the fact that the second term of the product (the difference of the word distribution and one hot vector of the decoded word) is a derivative of negative log likelihood of the decoded word. The reward function and the baseline are however treated as a constant, so they influence the derivate only multiplicatively.

`neuralmonkey.trainers.self_critical_objective.self_critical_objective` (*decoder: neural-monkey.decoders.decoder.Decoder, reward_function: typing.Callable[[numpy.ndarray, numpy.ndarray], numpy.ndarray], weight: float = None*)
 → *neural-monkey.trainers.generic_trainer.GenericTrainer*

Self-critical objective.

Parameters

- **decoder** – A recurrent decoder.
- **reward_function** – A reward function computing score in Python.
- **weight** – Mixing weight for a trainer.

Returns Objective object to be used in generic trainer.

`neuralmonkey.trainers.self_critical_objective.sentence_bleu` (*references: numpy.ndarray, hypotheses: numpy.ndarray*)
 → *numpy.ndarray*

Compute index-based sentence-level BLEU score.

Computes sentence level BLEU on indices outputed by the decoder, i.e. whatever the decoder uses as a unit is used a token in the BLEU computation, ignoring the tokens may be sub-word units.

`neuralmonkey.trainers.self_critical_objective.sentence_gleu` (*references:*
numpy.ndarray,
hypotheses:
numpy.ndarray)
 → `numpy.ndarray`

Compute index-based GLEU score.

GLEU score is a sentence-level metric used in Google's Neural MT as a reward in reinforcement learning (<https://arxiv.org/abs/1609.08144>). It is a minimum of precision and recall on 1- to 4-grams.

It operates over the indices emitted by the decoder which are not necessarily tokens (could be characters or subword units).

Module contents

Submodules

neuralmonkey.checking module

API checking module.

This module serves as a library of API checks used as assertions during constructing the computational graph.

exception `neuralmonkey.checking.CheckingException`

Bases: `Exception`

`neuralmonkey.checking.assert_same_shape` (*tensor_a:* `tensorflow.python.framework.ops.Tensor`, *tensor_b:* `tensorflow.python.framework.ops.Tensor`) → `None`

Check if two tensors have the same shape.

`neuralmonkey.checking.assert_shape` (*tensor:* `tensorflow.python.framework.ops.Tensor`, *expected_shape:* `typing.List[typing.Union[int, NoneType]]`) → `None`

Check shape of a tensor.

Parameters

- **tensor** – Tensor to be checked.
- **expected_shape** – Expected shape where *None* means the same as in TF and *-1* means not checking the dimension.

`neuralmonkey.checking.check_dataset_and_coders` (*dataset:* `neuralmonkey.dataset.Dataset`, *runners:* `typing.Iterable[neuralmonkey.runners.base_runner.BaseRunner]`) → `None`

neuralmonkey.dataset module

Implementation of the dataset class.

class `neuralmonkey.dataset.Dataset` (*name:* `str`, *series:* `typing.Dict[str, typing.List]`, *series_outputs:* `typing.Dict[str, str]`) → `None`

Bases: `collections.abc.Sized`

Base Dataset class.

This class serves as collection for data series for particular encoders and decoders in the model. If it is not provided a parent dataset, it also manages the vocabularies inferred from the data.

A data series is either a list of strings or a numpy array.

add_series (*name: str, series: typing.List[typing.Any]*) → None

batch_dataset (*batch_size: int*) → typing.Iterable[typing.Dataset]

Split the dataset into a list of batched datasets.

Parameters **batch_size** – The size of a batch.

Returns Generator yielding batched datasets.

batch_serie (*serie_name: str, batch_size: int*) → typing.Iterable[typing.Iterable]

Split a data serie into batches.

Parameters

- **serie_name** – The name of the series
- **batch_size** – The size of a batch

Returns Generator yielding batches of the data from the serie.

get_series (*name: str, allow_none: bool = False*) → typing.Iterable

Get the data series with a given name.

Parameters

- **name** – The name of the series to fetch.
- **allow_none** – If True, return None if the series does not exist.

Returns The data series.

Raises KeyError if the series does not exists and allow_none is False

has_series (*name: str*) → bool

Check if the dataset contains a series of a given name.

Parameters **name** – Series name

Returns True if the dataset contains the series, False otherwise.

series_ids

shuffle () → None

Shuffle the dataset randomly.

subset (*start: int, length: int*) → neuralmonkey.dataset.Dataset

```
class neuralmonkey.dataset.LazyDataset (name: str, series_paths_and_readers: typing.Dict[str, typing.Tuple[typing.List[str], typing.Callable[[typing.List[str]], typing.Any]]], series_outputs: typing.Dict[str, str], preprocessors: typing.List[typing.Tuple[str, str, typing.Callable]] = None) → None
```

Bases: *neuralmonkey.dataset.Dataset*

Implements the lazy dataset.

The main difference between this implementation and the default one is that the contents of the file are not fully loaded to the memory. Instead, everytime the function `get_series` is called, a new file handle is created and a generator which yields lines from the file is returned.

add_series (*name: str, series: typing.Iterable[typing.Any]*) → None

get_series (*name: str, allow_none: bool = False*) → typing.Iterable

Get the data series with a given name.

This function opens a new file handle and returns a generator which yields preprocessed lines from the file.

Parameters

- **name** – The name of the series to fetch.
- **allow_none** – If True, return None if the series does not exist.

Returns The data series.

Raises KeyError if the series does not exist and allow_none is False

has_series (*name: str*) → bool

Check if the dataset contains a series of a given name.

Parameters **name** – Series name

Returns True if the dataset contains the series, False otherwise.

series_ids

shuffle () → None

Do nothing, not in-memory shuffle is impossible.

TODO: this is related to the `__len__` method.

subset (*start: int, length: int*) → neuralmonkey.dataset.Dataset

`neuralmonkey.dataset.load_dataset_from_files` (*name: str = None, lazy: bool = False, preprocessors: typing.List[typing.Tuple[str, typing.Callable]] = None, **kwargs*) → neuralmonkey.dataset.Dataset

Load a dataset from the files specified by the provided arguments.

Paths to the data are provided in a form of dictionary.

Keyword Arguments

- **name** – The name of the dataset to use. If None (default), the name will be inferred from the file names.
- **lazy** – Boolean flag specifying whether to use lazy loading (useful for large files). Note that the lazy dataset cannot be shuffled. Defaults to False.
- **preprocessor** – A callable used for preprocessing of the input sentences.
- **kwargs** – Dataset keyword argument specs. These parameters should begin with `'s_'` prefix and may end with `'_out'` suffix. For example, a data series `'source'` which specify the source sentences should be initialized with the `'s_source'` parameter, which specifies the path and optionally reader of the source file. If runners generate data of the `'target'` series, the output file should be initialized with the `'s_target_out'` parameter. Series identifiers should not contain underscores. Dataset-level preprocessors are defined with `'pre_'` prefix followed by a new series name. In case of the pre-processed series, a callable taking the dataset and returning a new series is expected as a value.

Returns The newly created dataset.

Raises Exception when no input files are provided.

neuralmonkey.decorators module

neuralmonkey.decorators.**tensor** (*func*)

neuralmonkey.functions module

neuralmonkey.functions.**inverse_sigmoid_decay** (*param*, *rate*, *min_value*: *float* = 0.0, *max_value*: *float* = 1.0, *name*: *typing.Union[str, NoneType]* = None, *dtype=tf.float32*) → *tensorflow.python.framework.ops.Tensor*

Compute an inverse sigmoid decay: $k/(k+\exp(x/k))$.

The result will be scaled to the range (*min_value*, *max_value*).

Parameters

- **param** – The parameter *x* from the formula.
- **rate** – Non-negative *k* from the formula.

neuralmonkey.functions.**piecewise_function** (*param*, *values*, *changepoints*, *name=None*, *dtype=tf.float32*)

Compute a piecewise function.

Parameters

- **param** – The function parameter.
- **values** – List of function values (numbers or tensors).
- **changepoints** – Sorted list of points where the function changes from one value to the next. Must be one item shorter than *values*.

neuralmonkey.learning_utils module

neuralmonkey.learning_utils.**evaluation** (*evaluators*, *dataset*, *runners*, *execution_results*, *result_data*)

Evaluate the model outputs.

Parameters

- **evaluators** – List of tuples of series and evaluation functions.
- **dataset** – Dataset against which the evaluation is done.
- **runners** – List of runners (contains series ids and loss names).
- **execution_results** – Execution results that include the loss values.
- **result_data** – Dictionary from series names to list of outputs.

Returns Dictionary of evaluation names and their values which includes the metrics applied on respective series loss and loss values from the run.

neuralmonkey.learning_utils.**print_final_evaluation** (*name*: *str*, *eval_result*: *typing.Dict[str, float]*) → None

Print final evaluation from a test dataset.

```
neuralmonkey.learning_utils.run_on_dataset (tf_manager:          neural-
                                         monkey.tf_manager.TensorFlowManager;
                                         runners:                typing.
                                         List[neuralmonkey.runners.base_runner.BaseRunner],
                                         dataset:                neuralmonkey.dataset.Dataset,
                                         postprocess:            typing.
                                         Union[typing.List[typing.Tuple[str, typing.
                                         Callable]], NoneType], write_out: bool
                                         = False, batch_size: typing.Union[int, None-
                                         Type] = None, log_progress: int = 0) -> typing.
                                         Tuple[typing.List[neuralmonkey.runners.base_runner.ExecutionRes
                                         typing.Dict[str, typing.List[typing.Any]]]
```

Apply the model on a dataset and optionally write outputs to files.

Parameters

- **tf_manager** – TensorFlow manager with initialized sessions.
- **runners** – A function that runs the code
- **dataset** – The dataset on which the model will be executed.
- **evaluators** – List of evaluators that are used for the model evaluation if the target data are provided.
- **postprocess** – an object to use as postprocessing of the
- **write_out** – Flag whether the outputs should be printed to a file defined in the dataset object.
- **batch_size** – size of the minibatch
- **log_progress** – log progress every X seconds
- **extra_fetches** – Extra tensors to evaluate for each batch.

Returns Tuple of resulting sentences/numpy arrays, and evaluation results if they are available which are dictionary function -> value.

```
neuralmonkey.learning_utils.training_loop (tf_manager:          neural-
                                             monkey.tf_manager.TensorFlowManager,
                                             epochs:          int,      trainer:      neural-
                                             monkey.trainers.generic_trainer.GenericTrainer,
                                             batch_size: int, log_directory: str, evaluators:
                                             typing.List[typing.Union[typing.Tuple[str,
                                             typing.Any],          typing.Tuple[str,      str,
                                             typing.Any]]],          runners:      typ-
                                             ing.List[neuralmonkey.runners.base_runner.BaseRunner],
                                             train_dataset:      neural-
                                             monkey.dataset.Dataset, val_dataset:  typ-
                                             ing.Union[neuralmonkey.dataset.Dataset,
                                             typing.List[neuralmonkey.dataset.Dataset]],
                                             test_datasets:      typ-
                                             ing.Union[typing.List[neuralmonkey.dataset.Dataset],
                                             NoneType] = None, logging_period:
                                             typing.Union[str, int] = 20, valida-
                                             tion_period:      typing.Union[str, int] =
                                             500, val_preview_input_series:  typ-
                                             ing.Union[typing.List[str], NoneType] =
                                             None, val_preview_output_series:  typ-
                                             ing.Union[typing.List[str], NoneType] =
                                             None, val_preview_num_examples:  int
                                             = 15, train_start_offset: int = 0, run-
                                             ners_batch_size: typing.Union[int, NoneType]
                                             = None, initial_variables: typing.Union[str,
                                             typing.List[str], NoneType] = None, postproc-
                                             ess: typing.Union[typing.List[typing.Tuple[str,
                                             typing.Callable]], NoneType] = None) → None
```

Execute the training loop for given graph and data.

Parameters

- **tf_manager** – TensorFlowManager with initialized sessions.
- **epochs** – Number of epochs for which the algorithm will learn.
- **trainer** – The trainer object containing the TensorFlow code for computing the loss and optimization operation.
- **batch_size** – number of examples in one mini-batch
- **log_directory** – Directory where the TensorBoard log will be generated. If None, nothing will be done.
- **evaluators** – List of evaluators. The last evaluator is used as the main. An evaluator is a tuple of the name of the generated series, the name of the dataset series the generated one is evaluated with and the evaluation function. If only one series name is provided, it means the generated and dataset series have the same name.
- **runners** – List of runners for logging and evaluation runs
- **train_dataset** – Dataset used for training
- **val_dataset** – used for validation. Can be Dataset or a list of datasets. The last dataset is used as the main one for storing best results. When using multiple datasets. It is recommended to name them for better Tensorboard visualization.
- **test_datasets** – List of datasets used for testing

- **logging_period** – after how many batches should the logging happen. It can also be defined as a time period in format like: 3s; 4m; 6h; 1d; 3m15s; 3seconds; 4minutes; 6hours; 1days
- **validation_period** – after how many batches should the validation happen. It can also be defined as a time period in same format as logging
- **val_preview_input_series** – which input series to preview in validation
- **val_preview_output_series** – which output series to preview in validation
- **val_preview_num_examples** – how many examples should be printed during validation
- **train_start_offset** – how many lines from the training dataset should be skipped. The training starts from the next batch.
- **runners_batch_size** – batch size of runners. It is the same as batch_size if not specified
- **initial_variables** – variables used for initialization, for example for continuation of training
- **postprocess** – A function which takes the dataset with its output series and generates additional series from them.

neuralmonkey.logging module

class neuralmonkey.logging.Logging

Bases: object

static debug (*message: str, label: typing.Union[str, NoneType] = None*)

debug_disabled = []

debug_enabled = ['none']

static log (*message: str, color: str = 'yellow'*) → None

Log a message with a colored timestamp.

log_file = None

static log_print (*text: str*) → None

Print a string both to console and a log file if it is defined.

static notice (*message: str*) → None

Log a notice with a colored timestamp.

static print_header (*title: str, path: str*) → None

Print the title of the experiment and a set of arguments it uses.

static set_log_file (*path: str*) → None

Set up the file where the logging will be done.

strict_mode = None

static warn (*message: str*) → None

Log a warning.

neuralmonkey.logging.**debug** (*message: str, label: typing.Union[str, NoneType] = None*)

neuralmonkey.logging.**log** (*message: str, color: str = 'yellow'*) → None

Log a message with a colored timestamp.

`neuralmonkey.logging.log_print` (*text: str*) → None
Print a string both to console and a log file if it is defined.

`neuralmonkey.logging.notice` (*message: str*) → None
Log a notice with a colored timestamp.

`neuralmonkey.logging.warn` (*message: str*) → None
Log a warning.

neuralmonkey.run module

`neuralmonkey.run.default_variable_file` (*output_dir*)

`neuralmonkey.run.initialize_for_running` (*output_dir, tf_manager, variable_files*) → None
Restore either default variables or from configuration.

Parameters

- **output_dir** – Training output directory.
- **tf_manager** – TensorFlow manager.
- **variable_files** – Files with variables to be restored or None if the default variables should be used.

`neuralmonkey.run.main` () → None

neuralmonkey.tf_manager module

TensorFlow Manager.

TensorFlow manager is a helper object in Neural Monkey which manages TensorFlow sessions, execution of the computation graph, and saving and restoring of model variables.

```
class neuralmonkey.tf_manager.TensorFlowManager (num_sessions: int, num_threads: int, save_n_best: int = 1, minimize_metric: bool = False, variable_files: typing.Union[typing.List[str], NoneType] = None, gpu_allow_growth: bool = True, per_process_gpu_memory_fraction: float = 1.0, report_gpu_memory_consumption: bool = False, enable_tf_debug: bool = False) → None
```

Bases: object

Interface between computational graph, data and TF sessions.

sessions

List of active Tensorflow sessions.

```
execute (dataset: neuralmonkey.dataset.Dataset, execution_scripts, train=False, compute_losses=True, summaries=True, batch_size=None, log_progress: int = 0) → typing.List[neuralmonkey.runners.base_runner.ExecutionResult]
```

```
init_saving (vars_prefix: str) → None
```

```
initialize_model_parts (runners, save=False) → None  
Initialize model parts variables from their checkpoints.
```

```
restore (variable_files: typing.Union[str, typing.List[str]]) → None
```

restore_best_vars () → None
save (*variable_files*: *typing.Union[str, typing.List[str]]*) → None
validation_hook (*score*: *float*, *epoch*: *int*, *batch*: *int*) → None

neuralmonkey.tf_utils module

Small helper functions for TensorFlow.

`neuralmonkey.tf_utils.gpu_memusage` () → str
 Return ‘’ or a string showing current GPU memory usage.
 nvidia-smi result parsing based on <https://github.com/wookayin/gpustat>

`neuralmonkey.tf_utils.has_gpu` () → bool
 Check if TensorFlow can access GPU.

The test is based on <https://github.com/tensorflow/tensorflow/blob/master/tensorflow/python/platform/test.py>
 ...but we are interested only in CUDA GPU devices.

Returns True, if TF can access the GPU

neuralmonkey.train module

Training script for sequence to sequence learning.

`neuralmonkey.train.create_config` () → `neuralmonkey.config.configuration.Configuration`
`neuralmonkey.train.main` () → None

neuralmonkey.vocabulary module

Vocabulary class module.

This module implements the Vocabulary class and the helper functions that can be used to obtain a Vocabulary instance.

class `neuralmonkey.vocabulary.Vocabulary` (*tokenized_text*: *typing.List[str]* = *None*,
unk_sample_prob: *float* = *0.0*) → None

Bases: `collections.abc.Sized`

add_tokenized_text (*tokenized_text*: *typing.List[str]*) → None
 Add words from a list to the vocabulary.

Parameters **tokenized_text** – The list of words to add.

add_word (*word*: *str*, *occurences*: *int* = *1*) → None
 Add a word to the vocablulary.

Parameters

- **word** – The word to add. If it’s already there, increment the count.
- **occurences** – increment the count of word by the number of occurences

get_unk_sampled_word_index (*word*)
 Return index of the specified word with sampling of unknown words.

This method returns the index of the specified word in the vocabulary. If the frequency of the word in the vocabulary is 1 (the word was only seen once in the whole training dataset), with probability of `self.unk_sample_prob`, generate the index of the unknown token instead.

Parameters `word` – The word to look up.

Returns Index of the word, index of the unknown token if sampled, or index of the unknown token if the word is not present in the vocabulary.

get_word_index (*word: str*) → int
Return index of the specified word.

Parameters `word` – The word to look up.

Returns Index of the word or index of the unknown token if the word is not present in the vocabulary.

log_sample (*size: int = 5*)
Log a sample of the vocabulary.

Parameters `size` – How many sample words to log.

save_wordlist (*path: str, overwrite: bool = False, save_frequencies: bool = False, encoding: str = 'utf-8'*) → None
Save the vocabulary as a wordlist.

The file is ordered by the ids of words. This function is used mainly for embedding visualization.

Parameters

- **path** – The path to save the file to.
- **overwrite** – Flag whether to overwrite existing file. Defaults to False.
- **save_frequencies** – flag if frequencies should be stored. This parameter adds header into the output file.

Raises

- `FileExistsError` if the file exists and `overwrite` flag is
- `disabled`.

sentences_to_tensor (*sentences: typing.List[typing.List[str]], max_len: int = None, pad_to_max_len: bool = True, train_mode: bool = False, add_start_symbol: bool = False, add_end_symbol: bool = False*) → `typing.Tuple[numpy.ndarray, numpy.ndarray]`

Generate the tensor representation for the provided sentences.

Parameters

- **sentences** – List of sentences as lists of tokens.
- **max_len** – If specified, all sentences will be truncated to this length.
- **pad_to_max_len** – If True, the tensor will be padded to `max_len`, even if all of the sentences are shorter. If False, the shape of the tensor will be determined by the maximum length of the sentences in the batch.
- **train_mode** – Flag whether we are training or not (enables/disables unk sampling).
- **add_start_symbol** – If True, the `<s>` token will be added to the beginning of each sentence vector. Enabling this option extends the maximum length by one.

- **add_end_symbol** – If True, the `</s>` token will be added to the end of each sentence vector, provided that the sentence is shorter than `max_len`. If not, the end token is not added. Unlike `add_start_symbol`, enabling this option **does not alter** the maximum length.

Returns

A tuple of a sentence tensor and a padding weight vector.

The shape of the tensor representing the sentences is either $(batch_max_len, batch_size)$ or $(batch_max_len+1, batch_size)$, depending on the value of the `add_start_symbol` argument. `batch_max_len` is the length of the longest sentence in the batch (including the optional `</s>` token), limited by `max_len` (if specified).

The shape of the padding vector is the same as of the sentence vector.

truncate (*size: int*) → None

Truncate the vocabulary to the requested size.

The infrequent tokens are discarded.

Parameters size – The final size of the vocabulary

truncate_by_min_freq (*min_freq: int*) → None

Truncate the vocabulary only keeping words with a minimum frequency.

Parameters min_freq – The minimum frequency of included words.

vectors_to_sentences (*vectors: typing.List[typing.List[typing.List[str]]]*) → typing.List[typing.List[str]]

Convert vectors of indexes of vocabulary items to lists of words.

Parameters vectors – List of vectors of vocabulary indices.

Returns List of lists of words.

`neuralmonkey.vocabulary.from_bpe` (*path: str, encoding: str = 'utf-8'*) → `neuralmonkey.vocabulary.Vocabulary`

Load a vocabulary from Byte-pair encoding merge list.

NOTE: The frequencies of words in this vocabulary are not computed from data. Instead, they correspond to the number of times the subword units occurred in the BPE merge list. This means that smaller words will tend to have larger frequencies assigned and therefore the truncation of the vocabulary can be somehow performed (but not without a great deal of thought).

Parameters

- **path** – File name to load the vocabulary from.
- **encoding** – The encoding of the merge file (defaults to UTF-8)

`neuralmonkey.vocabulary.from_dataset` (*datasets: typing.List[neuralmonkey.dataset.Dataset], series_ids: typing.List[str], max_size: int, save_file: str = None, overwrite: bool = False, min_freq: typing.Union[int, NoneType] = None, unk_sample_prob: float = 0.5*) → `neuralmonkey.vocabulary.Vocabulary`

Load a vocabulary from a dataset with an option to save it.

Parameters

- **datasets** – A list of datasets from which to create the vocabulary
- **series_ids** – A list of ids of series of the datasets that should be used producing the vocabulary
- **max_size** – The maximum size of the vocabulary

- **save_file** – A file to save the vocabulary to. If None (default), the vocabulary will not be saved.
- **overwrite** – Overwrite existing file.
- **min_freq** – Do not include words with frequency smaller than this.
- **unk_sample_prob** – The probability with which to sample unks out of words with frequency 1. Defaults to 0.5.

Returns The new Vocabulary instance.

`neuralmonkey.vocabulary.from_file(*args, **kwargs)` → `neuralmonkey.vocabulary.Vocabulary`

`neuralmonkey.vocabulary.from_nematus_json(path: str, max_size: int = None, pad_to_max_size: bool = False)` → `neuralmonkey.vocabulary.Vocabulary`

Load vocabulary from Nematus JSON format.

The JSON format is a flat dictionary that maps words to their index in the vocabulary.

Parameters

- **path** – Path to the file.
- **max_size** – Maximum vocabulary size including ‘unk’ and ‘eos’ symbols, but not including <pad> and <s> symbol.

`neuralmonkey.vocabulary.from_wordlist(path: str, encoding: str = ‘utf-8’, contains_header: bool = True, contains_frequencies: bool = True)` → `neuralmonkey.vocabulary.Vocabulary`

Load a vocabulary from a wordlist.

The file can contain either list of words with no header. Or it can contain words and their counts separated by tab and a header on the first line.

Parameters

- **path** – The path to the wordlist file
- **encoding** – The encoding of the merge file (defaults to UTF-8)
- **contains_header** – if the file have a header on first line
- **contains_frequencies** – if the file contains frequencies in second column

Returns The new Vocabulary instance.

`neuralmonkey.vocabulary.initialize_vocabulary(directory: str, name: str, datasets: typing.List[neuralmonkey.dataset.Dataset] = None, series_ids: typing.List[str] = None, max_size: int = None)` → `neuralmonkey.vocabulary.Vocabulary`

Initialize a vocabulary.

This function is supposed to initialize vocabulary when called from the configuration file. It first checks whether the vocabulary is already loaded on the provided path and if not, it tries to generate it from the provided dataset.

Parameters

- **directory** – Directory where the vocabulary should be stored.
- **name** – Name of the vocabulary which is also the name of the file it is stored it.
- **datasets** – A a list of datasets from which the vocabulary can be created.

- **series_ids** – A list of ids of series of the datasets that should be used for producing the vocabulary.
- **max_size** – The maximum size of the vocabulary

Returns The new vocabulary

Module contents

The neuralmonkey package is the root package of this project.

1.7 Visualization

1.7.1 LogBook

Neural Monkey LogBook is a simple web application for preview the outputs of the experiments in the browser.

The experiment data are stored in a directory structure, where each experiment directory contains the experiment configuration, state of the git repository, the experiment was executed with, detailed log of the computation and other files necessary to execute the model that has been trained.

LogBook is meant as a complement to using *TensorBoard*, whose summaries are stored in the same directory structure.

How to run it

You can run the server using the following command:

```
bin/neuralmonkey-logbook --logdir=<experiments> --port=<port> --host=<host>
```

where *<experiments>* is the directory where the experiments are listed and *<port>* is the number of the port the server will run on, and *<host>* is the IP address of the host (defaults to 127.0.0.1, if you want the logbook to be visible to other computers in the network, set the host to 0.0.0.0)

Then you can navigate in your browser to *http://localhost:<port>* to view the experiment logs.

1.7.2 TensorBoard

You can use *TensorBoard* [<https://www.tensorflow.org/versions/r0.9/how_tos/summaries_and_tensorboard/index.html>](https://www.tensorflow.org/versions/r0.9/how_tos/summaries_and_tensorboard/index.html) to visualize your TensorFlow graph, see summaries of quantitative metrics about the execution of your graph, and show additional data like images that pass through it.

You can start it by following command:

```
tensorboard --logdir=<experiments>
```

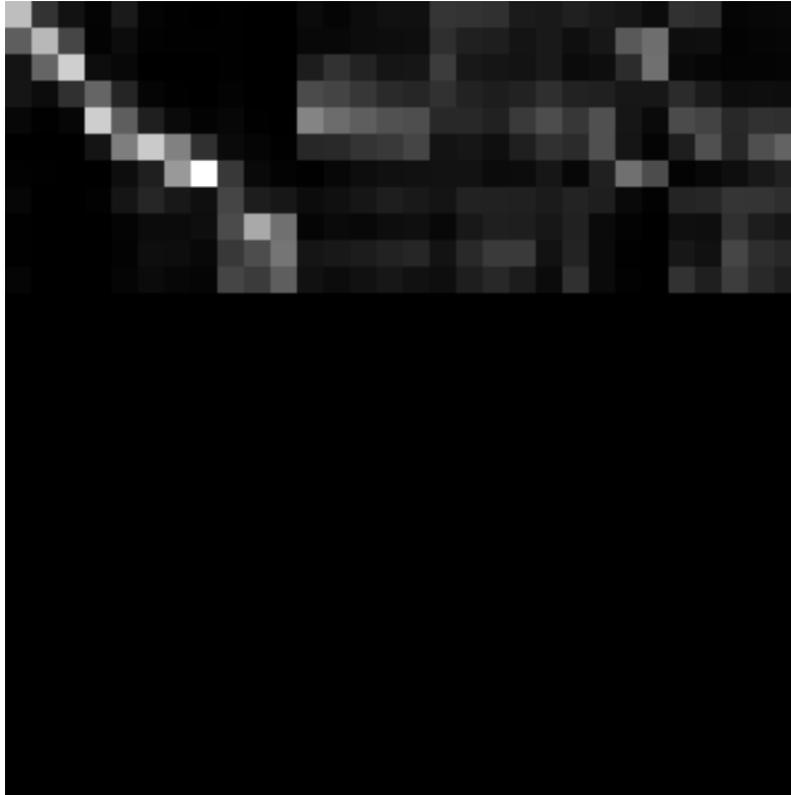
And then you can navigate in your browser to *http://localhost:6006/* (or if the TensorBoard assigns different port) and view all the summaries about your experiment.

How to read TensorBoard

The *step* in the TensorBoard is describing how many inputs (not batches) was processed.

1.7.3 Attention Visualization

If you are using an attention decoder, visualization of the soft alignment of each sentence in the first validation batch will appear in the *Images* tab in *TensorBoard*. The images might look like this:



Here, the source sentence is on the vertical axis and the target sentence on the horizontal axis. The size of each image is `max_output_len * max_input_len` so most of the time, there will be some blank rows at the bottom and some trailing columns with “phantom” attention (corresponding to positions after the end of the output sentence).

You can use the `tf_save_images.py` script to save the whole history of images as a sequence of PNG files:

```
# For the first sentence in the batch
scripts/tf_save_images.py events.out attention_0/image/0 --prefix images/attention_0_
```

Use `feh` to view the images as a time-lapse:

```
feh -g 300x300 -Z --force-aliasing --slideshow-delay 0.2 images/attention_0_*.png
```

Or enlarge them and turn them into an animated GIF using:

```
convert images/attention_0_*.png -scale 300x300 images/attention_0.gif
```

1.8 Advanced Features

1.8.1 Byte Pair Encoding

This is explained in *the machine translation tutorial*.

1.8.2 Dropout

Neural networks with a large number of parameters have a serious problem with an overfitting. Dropout is a technique for addressing this problem. The key idea is to randomly drop units (along with their connections) from the neural network during training. This prevents units from co-adapting too much. But during the test time, the dropout is turned off. More information in <https://www.cs.toronto.edu/~hinton/absps/JMLRdropout.pdf>

If you want to enable dropout on an encoder or on the decoder, you can simply add `dropout_keep_prob` to the particular section:

```
[encoder]
class=encoders.recurrent.SentenceEncoder
dropout_keep_prob=0.8
...
```

or:

```
[decoder]
class=decoders.decoder.Decoder
dropout_keep_prob=0.8
...
```

1.8.3 Pervasive Dropout

Detailed information in <https://arxiv.org/abs/1512.05287>

If you want allow dropout on the recurrent layer of your encoder, you can add `use_pervasive_dropout` parameter into it and then the dropout probability will be used:

```
[encoder]
class=encoders.recurrent.SentenceEncoder
dropout_keep_prob=0.8
use_pervasive_dropout=True
...
```

1.8.4 Attention Seeded by GIZA++ Word Alignments

todo: OC to reference the paper and describe how to use this in NM

1.9 Use SGE cluster array job for inference

To speed up the inference, the `neuralmonkey-run` binary provides the `--grid` option, which can be used when running the program as a SGE array job.

The `run` script make use of the `SGE_TASK_ID` and `SGE_TASK_STEPSIZE` environment variables that are set in each computing node of the array job. If the `--grid` option is supplied and these variables are present, it runs the inference only on a subset of the dataset, specified by the variables.

Consider this example `test_data.ini`:

```
[main]
test_datasets=[<dataset>]
variables=["path/to/variables.data"]
```

```
[dataset]
class=dataset.load_dataset_from_files
s_source="data/source.en"
s_target_out="out/target.de"
```

If we want to run a model configured in `model.ini` on this dataset, we can do:

```
neuralmonkey-run model.ini test_data.ini
```

And the program executes the model on the dataset loaded from `data/source.en` and stores the results in `out/target.de`.

If the source file is large or if you use a slow inference method (such as beam search), you may want to split the source file into smaller parts and execute the model on all of them in parallel. If you have access to a SGE cluster, you don't have to do it manually - just create an array job and supply the `--grid` option to the program. Now, suppose that the source file contains 100,000 sentences and you want to split it to 100 parts and run it on cluster. To accomplish this, just run:

```
qsub <qsub_options> -t 1-100000:1000 -b y \
"neuralmonkey-run --grid model.ini test_data.ini"
```

This will submit 100 jobs to your cluster. Each job will use its `SGE_TASK_ID` and `SGE_TASK_STEPSIZE` parameters to determine its part of the data to process. It then runs the inference only on the subset of the dataset and stores the result in a suffixed file.

For example, if the `SGE_TASK_ID` is 3, the `SGE_TASK_STEPSIZE` is 100, and the `--grid` option is specified, the inference will be run on lines 201 to 300 of the file `data/source.en` and the output will be written to `out/target.de.0000000200`.

After all the jobs are finished, you just need to manually run:

```
cat out/target.de.* > out/target.de
```

and delete the intermediate files. (Careful when your file has more than 10^{10} lines - you need to concatenate the intermediate files in the right order!)

1.10 GPU Benchmarks

We have done some benchmarks on our department to find out differences between GPUs and we have decided to share them here. Therefore they do not test speed of Neural Monkey, but they test different GPU cards with the same setup in Neural Monkey.

The benchmark test consisted of one epoch of Machine Translation training in Neural Monkey on a set of fixed data. The size of the model nicely fit into the 2GB memory, therefore GPUs with more memory could have better results with bigger models in comparison to CPUs. All GPUs have CUDA8.0

Setup (cc=cuda capability)	Running time
GeForce GTX 1080; cc6.1	9:55:58
GeForce GTX 1080; cc6.1	10:19:40
GeForce GTX 1080; cc6.1	12:34:34
GeForce GTX 1080; cc6.1	13:01:05
GeForce GTX Titan Z; cc3.5	16:05:24
Tesla K40c; cc3.5	22:41:01
Tesla K40c; cc3.5	22:43:10
Tesla K40c; cc3.5	24:19:45
16 cores Intel Xeon Sandy Bridge 2012 CPU	46:33:14
16 cores Intel Xeon Sandy Bridge 2012 CPU	52:36:56
Quadro K2000; cc3.0	59:47:58
8 cores Intel Xeon Sandy Bridge 2012 CPU	60:39:17
GeForce GT 630; cc3.0	103:42:30
8 cores Intel Xeon Westmere 2010 CPU	134:41:22

1.11 Development Guidelines

1.11.1 Github Workflow

This is a brief document about the Neural Monkey development workflow. Its primary aim is to describe the environment around the Github repository (e.g. continuous integration tests, documentation), pull requests, code-review, etc.

This document is written chronologically, from the point of view of a contributor.

Creating an issue

Everytime there is a need to change the codebase, the contributor should create a corresponding issue in the [Github repository](#).

The name of the issue should be comprehensive, and should summarize the issue in less than 10 words. In the issue description, all the relevant information should be mentioned, and, if applicable, a sketch of the solution should be given so the fashion and method of the solution can be subject to further discussion.

Labels

There is a number of label tags to use to provide an easier way to orient among the issues. Here is an explanation of some of them, so they are not used incorrectly (notably, there is a slight difference between “enhancement” and “feature”).

- **bug:** Use when there is something wrong in the current codebase that needs to be fixed. For example, “Random seeds are not working”
- **documentation:** Use when the main topic of the issue or pull request is to contribute to the documentation (be it a rst document or a request for more docstrings)
- **tests:** Similarly to documentation, use if the main topic of the issue is to write a test or to do changes to the testing process itself.
- **feature:** A request for implementing a feature regarding the training of the models or the models themselves, e.g. “Minimum risk training” or “Implementation of conditional GRU”.

- **enhancement:** A request for implementing a feature to Neural Monkey aimed at improving the user experience with the package, e.g. “GPU profiling” or “Logging of config building”.
- **help wanted:** Used as an additional label, which specify that solving the issue is suitable either for new contributors or for researchers who want to try out a feature, which would be otherwise implemented after a longer time.
- **refactor:** Refactor issues are requests for cleaning the codebase, using better ways to achieve the same results, conforming to a future API, etc. For example, “Rewrite decoder using decorators”

Todo

Replace text with label pictures from Github

Selecting an issue to work on and assigning people

Note: If you want to start working on something and don’t have a preference, check out the issues labeled “Help wanted”

When you decide to work on an issue, assign yourself to it and describe your plans on how you will proceed (in case there is no solution sketch provided in the issue description). This way, others may comment on your plans prior to the work, which can save a lot of time.

Please make sure that you put all additional information as a comment to the issue in case the issue has been discussed elsewhere.

Creating a branch

Prior to writing code (or at least before the first commit), you should create a branch for solution of the issue. This command creates a new branch called `your_branch_name` and switches your working copy to that branch:

```
$ git checkout -b your_branch_name
```

Writing code

On the new branch, you can make changes and commit, until your solution is done.

It is worth noting that we are trying to keep our code clean by enforcing some code writing rules and guidelines. These are automatically check by Travis CI on each push to the Github repository. Here is a list of tools used to check the quality of the code:

- [pylint](#)
- [pycodestyle](#)
- [mypy](#)
- [markdownlint](#)

Todo

provide short description to the tools, check that markdownlint has correct URL

You can run the tests on your local machine by using scripts (and requirements) from the `tests/` directory of this package,

This is a usual mantra that you can use for committing and pushing to the remote branch in the repository:

```
$ git add .
$ git commit -m 'your commit message'
$ git push origin your_branch_name
```

Note: If you are working on a branch with someone else, it is always a good idea to do a `git pull --rebase` before pushing. This command updates your branch with remote changes and apply your new commits on top of them.

Warning: If your commit message contains the string `[ci skip]` the continuous integration tests are not run. However, try not to use this feature unless you know what you're doing.

Creating a pull request

Whenever you want to add a feature or push a bugfix, you should make a new pull request, which can be reviewed and merged by someone else. The typical workflow should be as follows:

1. Create a new branch, make your changes and push them to the repository.
2. You should now see the new branch on the Github project page. When you open the branch page, click on “Create Pull request” button.
3. When the pull request is created, the continuous integration tests are run on Travis. You can see the status of the test run on the pull request page. There is also a link to Travis so you can inspect the results of the test run, and make additional changes in order to make the tests successful, if needed. Additionally to the code quality checking tools, unit and regression tests are run as well.

When you create a pull request, assign one or two people to do the review.

Code review and merging

Your pull requests should always be subject to code review. After you create the pull request, select one or two contributors and assign them to make a review.

This phase consists of discussion about the introduced changes, suggestions, and another requirements made by the reviewers. Anyone who wants to do a review can contribute, the reviewer roles are not considered exclusive.

After all of the reviewers' comments have been addressed and the reviewers approved the pull request, the pull request can be merged. It is usually a good idea to rebase the code to the recent version of master. Assuming your working copy is switched to the **master** branch, do:

```
$ git pull --rebase
$ git checkout your_branch_name
$ git rebase master
```

These commands first update your local copy of master from the remote repository, then switch your working copy to the `your_branch_name` branch, and then rebases the branch on the updated master.

Rebasing is a process in which commits from a branch (`your_branch_name`) are applied on a second branch (master), and the new HEAD is marked as the first branch.

Warning: Rebasing is a process which overwrites history. Therefore be absolutely sure that you know what are you doing. Usually if you work on a branch alone, rebasing is a safe procedure.

When the branch is rebased, you have to force-push it to the repository:

```
$ git push -f origin your_branch_name
```

This command overwrites the your branch in the remote repository with your local branch (which is now rebased on master, and therefore, up-to-date)

Note: You can use rebasing also for updating your branch to work with newer versions of master instead of merging the master in the branch. Bear in mind though, that you should force-push these updates, so no-one works on the outdated version of the branch.

Finally, one more round of tests is run and if everything is OK, you can click the “Merge pull request” button, which executes the merge. You can also click another button to delete the `your_branch_name` branch from the repository after the merge.

Documentation

Documentation related to GitHub is written in [Markdown](#) files, Python documentation using [reStructuredText](#). This concerns both the standalone documents (in `/docs/`) and the docstrings in source code.

Style of the Markdown files is automatically checked using [Markdownlint](#).

1.11.2 Running tests

Every time a commit is pushed to the Github [repository](#), the tests are run on [Travis CI](#).

If you want to run the tests locally, install the required tools:

```
(nm)$ pip install --upgrade -r <(cat tests/*_requirements.txt)
```

Test scripts

Test scripts located in the `tests` directory:

- `tests_run.sh` runs training with small dataset and `small.ini` configuration
- `unit-tests_run.sh` runs unit tests
- `lint_run.sh` runs pylint
- `mypy_run.sh` runs mypy

All the scripts should be run from the main directory of the repository. There is also `run_tests.sh` in the main directory, that runs all the tests above.

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